

SECTION 6.4: VECTORS AND DOT PRODUCTS

Assume $v_1, v_2, w_1,$ and w_2 are real numbers. For now, we will deal with vectors in the plane.

PART A: DOT PRODUCTS

How do we multiply vectors? There are two common types of products of vectors: the dot product (also known as the Euclidean inner product), and the cross product (also known as the vector product).

Dot Product (Algebraic Definition)

If $\mathbf{v} = \langle v_1, v_2 \rangle$ and $\mathbf{w} = \langle w_1, w_2 \rangle$, then the dot product of \mathbf{v} and \mathbf{w} is given by:

$$\mathbf{v} \bullet \mathbf{w} = v_1 w_1 + v_2 w_2$$

In words, you add the products of corresponding components. Dot products, themselves, are scalars.

Example

$$\begin{aligned} \langle 7, 3 \rangle \bullet \langle 2, -4 \rangle &= (7)(2) + (3)(-4) \\ &= 14 - 12 \\ &= 2 \end{aligned}$$

PART B: PROPERTIES OF THE DOT PRODUCT

See p.440 in Larson. All but [Property #4](#) are shared by the operation of multiplication of real numbers.

[Property #1](#)) The dot product is commutative: $\mathbf{v} \bullet \mathbf{w} = \mathbf{w} \bullet \mathbf{v}$

[Property #3](#)) The dot product distributes over vector addition: $\mathbf{a} \bullet (\mathbf{b} + \mathbf{c}) = \mathbf{a} \bullet \mathbf{b} + \mathbf{a} \bullet \mathbf{c}$

[Property #4](#)) Relating dot product and vector length: $\mathbf{v} \bullet \mathbf{v} = \|\mathbf{v}\|^2$

Observe that both sides equal $v_1^2 + v_2^2$.

PART C: THE ANGLE BETWEEN TWO VECTORS

Given two nonzero vectors \mathbf{v} and \mathbf{w} , let θ be the angle between them (i.e., between their position vectors) that is in the interval $[0^\circ, 180^\circ]$.

$$\cos \theta = \frac{\mathbf{v} \bullet \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|}$$

Think: The dot product over the product of the lengths.

The proof employs the Law of Cosines.

Note: Again, books avoid the \cos^{-1} notation here, because angles between vectors are often given in degrees. The \cos^{-1} button works nicely, though, because (if you are in DEGREE mode), you are guaranteed to get an angle in $[0^\circ, 180^\circ]$.

Note: Observe that the formula is symmetric in \mathbf{v} and \mathbf{w} , so it doesn't matter which way you name the vectors.

Technical Note: The Cauchy-Schwarz Inequality guarantees that the right-hand side of the formula is a value in $[-1, 1]$.

Two vectors \mathbf{v} and \mathbf{w} are orthogonal $\Leftrightarrow \mathbf{v} \bullet \mathbf{w} = 0$.

This happens \Leftrightarrow Either vector is $\mathbf{0}$, the zero vector $\langle 0, 0 \rangle$ in the plane, or if $\theta = 90^\circ$. The terms “orthogonal” and “perpendicular” are frequently interchangeable.

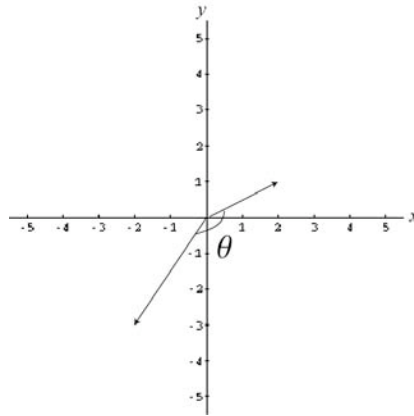
We say that $\mathbf{0}$ is orthogonal to every vector in the plane.

Example

Find the angle between $\mathbf{v} = \langle 2, 1 \rangle$ and $\mathbf{w} = \langle -2, -3 \rangle$ to the nearest tenth of a degree.

Solution

(Optional sketch:)



$$\begin{aligned} \cos \theta &= \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|} \\ &= \frac{\langle 2, 1 \rangle \cdot \langle -2, -3 \rangle}{\|\langle 2, 1 \rangle\| \|\langle -2, -3 \rangle\|} \\ &= \frac{-4 - 3}{\sqrt{(2)^2 + (1)^2} \sqrt{(-2)^2 + (-3)^2}} \\ &= \frac{-7}{\sqrt{5} \sqrt{13}} \\ &= -\frac{7}{\sqrt{65}} \quad (\approx -0.868) \end{aligned}$$

Make sure you are in DEGREE mode on your calculator.
Press the \cos^{-1} button.

$$\begin{aligned} \theta &= \cos^{-1} \left(-\frac{7}{\sqrt{65}} \right) \\ \theta &\approx 150.3^\circ \end{aligned}$$

PART D: WORK

The work W applied on an object by a constant force \mathbf{F} as the object moves along the displacement vector \mathbf{d} is given by: $W = \mathbf{F} \cdot \mathbf{d}$

Preliminaries: Dot Product (Geometric Definition)

From [Notes 6.29](#), we had: $\cos \theta = \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|}$

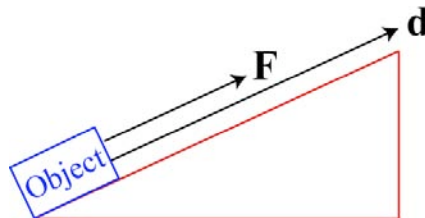
We can solve for $\mathbf{v} \cdot \mathbf{w}$ and obtain a geometric definition for the dot product:

$$\mathbf{v} \cdot \mathbf{w} = \|\mathbf{v}\| \|\mathbf{w}\| \cos \theta$$

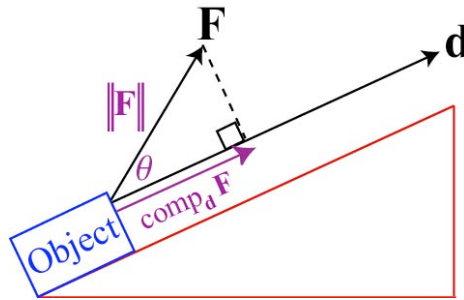
Reasoning Behind the Work Formula

If the force \mathbf{F} being applied acts in the same direction as the direction of motion (i.e., the direction of \mathbf{d}), then the work done is given by:

$$\begin{aligned} W &= (\text{magnitude of force})(\text{distance traveled}) \\ &= \|\mathbf{F}\| \|\mathbf{d}\| \end{aligned}$$



In general, if \mathbf{F} does not necessarily act in the same direction as \mathbf{d} , then we replace the magnitude of \mathbf{F} , denoted by $\|\mathbf{F}\|$, with the component of \mathbf{F} in the direction of \mathbf{d} , denoted by $\text{comp}_{\mathbf{d}}\mathbf{F}$. The latter represents the “relevant aspect” of the force in the direction of motion.



The work done is given by:

$$\begin{aligned}
 W &= (\text{comp}_{\mathbf{d}}\mathbf{F})(\text{distance traveled}) \\
 &= (\|\mathbf{F}\|\cos\theta)(\|\mathbf{d}\|) \\
 &= \|\mathbf{F}\|\|\mathbf{d}\|\cos\theta \\
 &= \mathbf{F} \cdot \mathbf{d} \\
 &\quad \text{(by the Geometric Definition of Dot Product)}
 \end{aligned}$$

In Calculus: You will discuss the work applied on an object by a nonconstant (or variable) force field as the object moves along a nonlinear path, or even a path in three-dimensional space. You see this in [Calculus III: Math 252 at Mesa](#).

Note: The ideas of this section extend naturally to three dimensions and (for the algebraic perspective on dot products) even higher dimensions.