

CH. 18: VECTOR CALCULUS

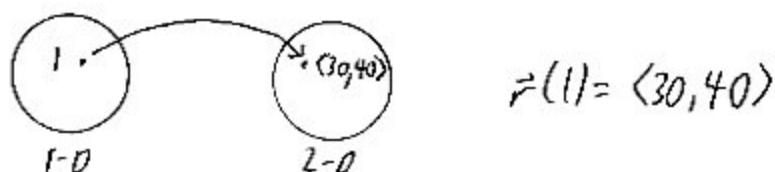
We'll look at extensions of the Fund. Thm. of Calculus (FTC) from Calc I !!

18.1: VECTOR FIELDS

① Intro

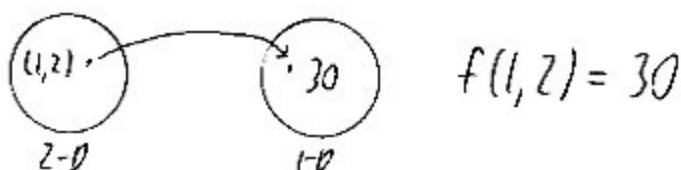
Ch. 15

VVF $\vec{r}: D, \text{ a subset of } \mathbb{R} \rightarrow V_n \text{ (or } \mathbb{R}^n)$



Ch. 16

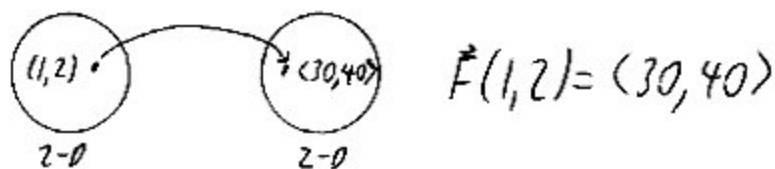
Scalar func. $f: D, \text{ a subset of } \mathbb{R}^n \rightarrow \mathbb{R}$



Now

A vector field is described by a

VVF $\vec{F}: D, \text{ a subset of } \mathbb{R}^n \rightarrow V_n \text{ (or } \mathbb{R}^n)$



We use P
in $\vec{F} = \langle M, N, P \rangle$
in \mathbb{R}^3 .

Every point A in a region D gets a vector $\vec{F}|_A$.
 (x, y) $\vec{F}(x, y)$
 (x, y, z) $\vec{F}(x, y, z)$

We'll study steady vector fields, in which vectors do not change with time.

Ex Velocity field for a kitchen sink (See 18.3.9, Note 2)

Show some of the vectors, enough to show a pattern.

Use A as the initial point for \vec{F}_A .



Sample units:
 $\langle \frac{m}{sec}, \frac{m}{sec} \rangle$

Ex Electromagnetic force fields
 Gravitational

Ex (Ch. 16) Gradient vector field

Ex $f(x,y) = x^2 + y^2$ (Ch. 16) (Ch. 18)
 $\vec{F}(x,y) = \vec{\nabla} f(x,y) = \langle 2x, 2y \rangle$ (18.3)

We call f a potential function for \vec{F} .
 \uparrow $-f$ in Physics so that: $\vec{F} = \vec{\nabla} f$ (Higher pot.)

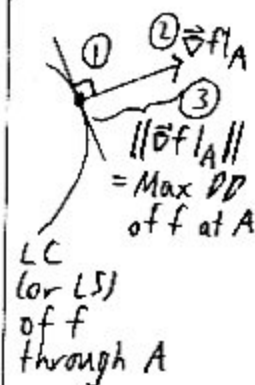
We call \vec{F} a conservative vector field, because
 $\vec{F} = \vec{\nabla} f$ for some scalar func. f
 (i.e., \vec{F} has a potential function).

Given a scalar
 multivariable
 func. in Ch. 16,
 what vector
 field did we
 construct?
 VVF

Like the 609-
 must be
 conservative
 to have potential.

Recall (from 16.6):

- ① $\underbrace{\vec{\nabla} f|_A}_{= \vec{F}|_A \text{ here}} \perp$ level curve/surface^{LC} of the potential f containing A ^{LS}
- ② $\vec{\nabla} f|_A$ points in direction of max rate of \nearrow of f at A .
- ③ Its length, $\|\vec{\nabla} f|_A\|$ is that max rate of \nearrow .

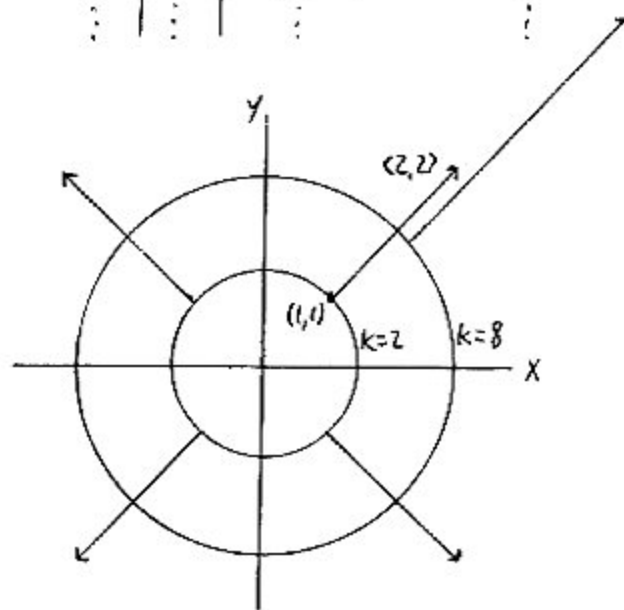


Table

(LC thru A)

$\vec{F}|_A$
 $\vec{\nabla} f|_A$

A		$\vec{F}(x,y) =$ $\vec{\nabla} f(x,y) =$ $\langle 2x, 2y \rangle$	$k =$ $f(x,y) =$ $x^2 + y^2$
x	y		
1	1	$\langle 2, 2 \rangle$	2
-1	1	$\langle -2, 2 \rangle$	2
2	2	$\langle 4, 4 \rangle$	8
\vdots	\vdots	\vdots	\vdots



(B) $\vec{\nabla}$ Operator
del/nabla

$$\vec{\nabla} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \quad (\text{Informal})$$

$$\vec{\nabla} f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle \quad \text{gives a VVF (vector field)} \quad \left. \begin{array}{l} \mathbb{R}^3 \\ \text{versions} \end{array} \right\}$$

\uparrow
scalar
func.

How does $\vec{\nabla}$ operate on VVFs?

(Assume \vec{F} is "nice": components are cont. and have cont. 1st-order PDs where we care.)

(C) $\overrightarrow{\text{curl}} \vec{F} = \vec{\nabla} \times \vec{F} \quad (\vec{F} \text{ in } \mathbb{R}^3) \quad \left(\begin{array}{l} \text{If } \vec{F} = \langle F_1, F_2 \rangle \text{ in } \mathbb{R}^2, \\ \text{write } \langle F_1, F_2, 0 \rangle \end{array} \right)$

\nwarrow zero

gives a VVF (vector field)

Ex (#18) If $\vec{F}(x, y, z) = \langle \underbrace{x^3 \ln z}_{M(x, y, z)}, \underbrace{x e^{-y}}_{N(x, y, z)}, \underbrace{-(y^2 + 2z)}_{P(x, y, z)} \rangle$,
find $\text{curl } \vec{F}$.

$$\overrightarrow{\text{curl}} \vec{F} = \vec{\nabla} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^3 \ln z & x e^{-y} & -(y^2 + 2z) \end{vmatrix}$$

$$= \left\langle \frac{\partial}{\partial y} [-(y^2 + 2z)] - \frac{\partial}{\partial z} (x e^{-y}) \right\rangle$$

$$\ominus \left[\frac{\partial}{\partial x} [-(y^2 + 2z)] - \frac{\partial}{\partial z} (x^3 \ln z) \right],$$

$$\frac{\partial}{\partial x} (x e^{-y}) - \frac{\partial}{\partial y} (x^3 \ln z) \rangle$$

$$= \langle -2y, x^3 \cdot \frac{1}{z}, e^{-y} \rangle$$

$$= \boxed{\langle -2y, \frac{x^3}{z}, e^{-y} \rangle}$$

Marsden uses C^1 instead of "nice".
"Smooth" implies derivs non-0, perhaps.

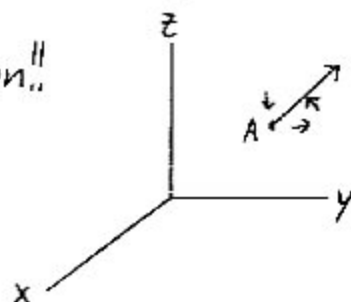
In 18.7,
Suokowski says
 $\text{rot } \vec{F} = (\overrightarrow{\text{curl}} \vec{F}) \cdot \vec{n}$

where \vec{F} =
velocity $\nabla \phi$

Explained
on pp. 1013-4
using Stokes
Thm. in 18.7.

① Interpreting $[\text{curl } \vec{F}]_A$ (in a coordinate-free sense)

"Local" rotation!!



Don't need Cartesian!

$[\text{curl } \vec{F}]_A$
vorticity vector

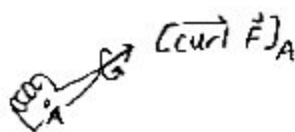
Note: \vec{F}_A , itself, is
irrelevant!! (limit idea)

Direction of $[\text{curl } \vec{F}]_A$ indicates the axis of rotation
of \vec{F} near A .

which way does $[\text{curl } \vec{F}]_A$ point?

Right-Hand Rule for curl

rotation is
counter-
clockwise
if look
from
tip of curl
vector towards
the paddlewheel

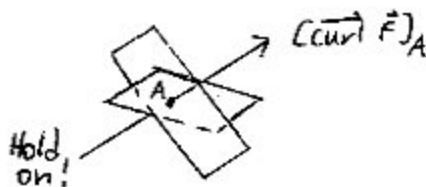


curling of fingers
indicate "overall rotation" (see \downarrow)
of \vec{F} near A

Idea

Analogous to
idea of
ODs at A
max'd in
direction of
 $\nabla \phi|_A$

At A , rotate this paddlewheel until its paddles
revolve the fastest



$\|[\text{curl } \vec{F}]_A\|$ indicates the strength of the rotational effect about
near A . It equals twice the angular speed of the
paddles about this axis. Sample units: $\frac{\text{radians}}{\text{sec}}$ Time unit
used for \vec{F}
 $\text{curl } \vec{F} = \vec{0}$ throughout $D \Leftrightarrow \vec{F}$ is irrotational in D

see
Snook 1016,
MIT Munkres
Calc II - F9
see HW

$$\textcircled{E} \operatorname{div} \vec{F} = \vec{\nabla} \cdot \vec{F}$$

divergence gives a scalar function

Ex (#18) If $\vec{F}(x, y, z) = \langle x^3 \ln z, x e^{-y}, -(y^2 + 2z) \rangle$,
find $\operatorname{div} \vec{F}$.

$$\operatorname{div} \vec{F} = \vec{\nabla} \cdot \vec{F}$$

$$= \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle x^3 \ln z, x e^{-y}, -(y^2 + 2z) \rangle$$

$$= \frac{\partial}{\partial x} (x^3 \ln z) + \frac{\partial}{\partial y} (x e^{-y}) + \frac{\partial}{\partial z} [-(y^2 + 2z)]$$

$$= 3x^2 \ln z + x e^{-y}(-1) + (-2)$$

$$= \boxed{3x^2 \ln z - x e^{-y} - 2}$$

Explained
using Div. Thm.
in 18.6
Stewart 1094
Sec ET

Ex Interpreting $[\operatorname{div} \vec{F}]_A$ (again, in terms of local behavior near A)

tendency of fluid to diverge from pt. A

If $[\operatorname{div} \vec{F}]_A < 0$, then there is a sink at A .

Tendency $\begin{array}{c} \nearrow A \leftarrow \\ \rightarrow A \rightarrow \end{array}$ } alphabetical
order $\approx -$ to $+$

If $[\operatorname{div} \vec{F}]_A > 0$, then there is a source at A .

$\begin{array}{c} \nwarrow A \rightarrow \\ \rightarrow A \rightarrow \end{array}$

Ex cooling
gas -
compressible

If $[\operatorname{div} \vec{F}]_A = 0 \Rightarrow$ neither. $\begin{array}{c} \rightarrow A \rightarrow \\ \rightarrow A \rightarrow \end{array}$

If $\operatorname{div} \vec{F} = 0$ throughout $D \Rightarrow \vec{F}$ is divergence free.

Exs incompressible fluids,
solenoidal electromagnetic fields
(EM)

See 18.6.1 for units.

incl. water,
pretty much

⑥ When is a Vector Field \vec{F} Conservative?

(Assume \vec{F} is "nice.")

$$\Leftrightarrow \vec{F} = \vec{\nabla} f \text{ for some scalar func. } f$$

$$\Leftrightarrow \overrightarrow{\text{curl}} \vec{F} = \vec{0} \quad (\text{if } \vec{F} \text{ nice in } \mathbb{R}^3)$$

(You'll prove \Rightarrow in HW! #22 Converse (\Leftarrow) proven later in 18.7 on Stokes's Thm.)

Marsden Sed
p. 551;
In \mathbb{R}^3 , \vec{F} can
be conserv.
even if undef.
at a finite #
of pts.
(provided f
also undef.
there).
Exceptional
pts. not
allowed in \mathbb{R}^2 .

Larson: This is related to conservation of energy.
For a particle moving in a conservative force field,
the sum of its kinetic energy
due to motion
and its potential energy
due to position
is constant.

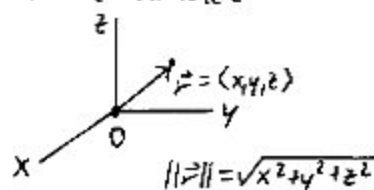
(H) Inverse Square Fields are Conservative

Ex Gravity, Electric force (Coulomb's Law)



The magnitude of the force between these is inversely proportional to the square of the distance between them. Let one be at O.

2x distance $\Rightarrow \frac{1}{4}$ of force
3 $\frac{1}{9}$

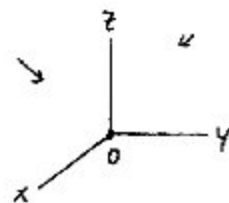
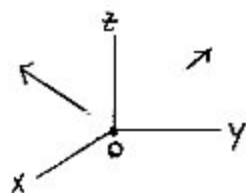


$$\vec{F}(x, y, z) = \underbrace{\left(\frac{c}{\|\vec{r}\|^2}\right)}_{\text{unit vector in direction of } \vec{r}} \underbrace{\left(\frac{\vec{r}}{\|\vec{r}\|}\right)}_{\text{unit vector in direction of } \vec{r}} \text{ for some constant of proportionality, } c.$$

ensures that $\|\vec{F}(x, y, z)\| = \frac{|c|}{\|\vec{r}\|^2}$

$$= \frac{c\vec{r}}{\|\vec{r}\|^3}, \text{ provided } \vec{r} \neq \vec{0}$$

If $c > 0$, repulsion (away from O) If $c < 0$, attraction (towards O)



These vectors are \perp to spheres centered at O,



level surfaces of potential

In \mathbb{R}^3 , so OK that 'O' is an exceptional pt.

Stewart sect. 14.1, p. 1041, 3:

If \vec{F} comp's, f have cont. 2nd-order p.d.s

\vec{F} is conserv. : $\vec{F} = \nabla f$, where $f(x, y, z) = -\frac{c}{\|\vec{r}\|}$ (✓ this!!)

(I) Interesting IDs (in \mathbb{R}^3)

$$\begin{aligned} \operatorname{div}(\operatorname{curl} \vec{F}) &= 0 \\ \operatorname{curl}(\nabla f) &= \vec{0} \quad (\text{see 18.1.3 figure}) \\ &\text{is conserv., remember?} \end{aligned}$$

$\operatorname{div}, \operatorname{curl}$ critical to Maxwell's Laws in EM!!

Marsden
5ed, 290-2Ⓜ Flow Lines

(or Streamlines or Integral Curves)

If \vec{F} is a velocity field, then a particle placed in the field will trace out a flow line.

(See 15.2.2)



Flow line carries "invisible" speed info.

If that's the path we want, how much does \vec{F} help us?

What if we want another path?

Even if there's a flow line from pt. A to pt. B, can we do better?

We'll discuss Work in 18.2ⓔ.

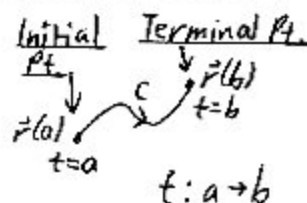
18.2: LINE (PATH) S

We'll do 2D, but this extends to 3D easily.

(A) Smooth Curves

$\vec{r}(t) = \langle x(t), y(t) \rangle$ gives a smooth parameterization of a curve, C , on $[a, b]$

i.e., when $a \leq t \leq b$



$\Leftrightarrow \vec{r}'(t) = \left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle$, a tangent VVF, is

- ① cont. on $[a, b]$, and
- ② never $\vec{0}$ on (a, b)

Then, C is a smooth curve with no breaks, corners, or cusps.

\vec{r} can't backtrack.

my notation

(B) Piecewise-Smooth (ps) Curves

can be partitioned into a finite # of smooth curves.



$$C = C_1 \cup C_2 \cup C_3$$

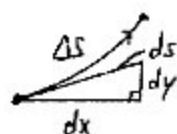
union

© Mass, m , of a ps Wire, C

Recall (15.1)

ds = differential of arc length " s "

In Δt time,



$$ds \approx \Delta s$$

In 3D
 $\sqrt{\dots + (dz)^2}$

$$= \sqrt{(dx)^2 + (dy)^2} \quad (\text{Informal})$$

$$\sqrt{\dots + \left(\frac{dz}{dt}\right)^2}$$

$$= \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \quad (\text{If } t \nearrow; \text{ otherwise, } "|dt|")$$

$$= \|\vec{r}'(t)\| dt \quad \text{or} \quad \underbrace{\|\vec{v}(t)\|}_{\text{speed}} \underbrace{dt}_{\text{change in time}}$$

distance covered

Arc Length of $C = \int_C ds$

$$= \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$



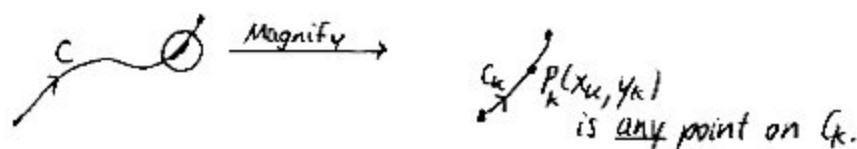
Now

Let $\delta(x,y)$ be the linear mass density of a wire at (x,y) .

(Assume density is constant in a cross-section.)

Idea

Break C into tiny arcs.



$\delta \approx$ constant on C_k . tiny!
 C_k : cover length Δs_k
 in time Δt_k

$$\begin{aligned} \text{Mass of } C_k &\approx (\text{Density at } P_k) (\text{Arc length of } C_k) \\ &= [\delta(x_k, y_k)] [\Delta s_k] \end{aligned}$$

$$\boxed{\text{Mass, } m, \text{ of } C = \int_C \delta(x,y) ds}$$

Why?

$$\int_C \delta(x,y) ds = \lim_{\substack{\|P\| \rightarrow 0 \\ \text{largest } \Delta t_k}} \underbrace{\sum_k \delta(x_k, y_k) \Delta s_k}_{\substack{\text{Riemann sum} \\ \text{Mass of } C_k \\ \text{Approx. for } m}}$$

This is an example of a...

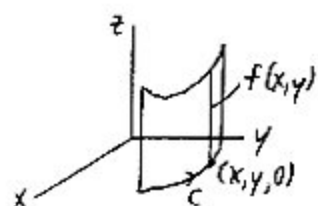
Stewart
Se, ET 1062:
Invented in
early 19c to
study forces,
fluid flow, EM

① Line (Path) Integral

$$\int_C f(x,y) ds$$

If $f(x,y) = 1 \Rightarrow$ Arc length of C
If $f(x,y) = \delta(x,y) \Rightarrow$ Mass of C

Lateral Surface Area ("Wall")



if $f(x,y) \geq 0$ along C

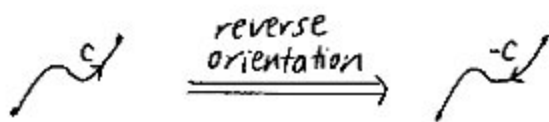
DETAILS...

Note 1: (We assume C is ps, and f is cont.
on a region containing C .)



Note 2: We get the same value for $\int_C f(x,y) ds$,
regardless of how we parameterize C .
if smooth

Even the orientation doesn't matter:



$$\int_C f(x,y) ds = \int_{-C} f(x,y) ds$$

\Leftarrow Expand
using $|dt|$

If $\Delta s_k = 0$
 $\Rightarrow \vec{r}' = 0$ on C there,
lose "smooth"

Stewart
Se, ET 1067: \rightarrow
Remember $|dt|$
from ds

Always true: $\Delta s_k \geq 0$, mass ≥ 0

We flip sign if we had dx, dy, \dots

$$\left(\text{eg, } \int_a^b f(t) dt = - \int_b^a f(t) dt \right)$$

$t: a \rightarrow b$ $t: b \rightarrow a$ for otherwise same param.

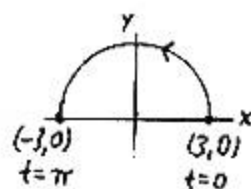
Like Ex 3

Ex Find the mass of a wire C if the density at $P(x,y)$ is directly proportional to its distance from the x -axis, and C is parameterized by $x = -3\cos t$, $y = 3\sin t$; $0 \leq t \leq \pi$.
(Assume $t: 0 \rightarrow \pi$; $t \uparrow$ consistently w/orientation)

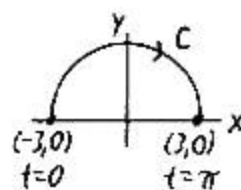
Sol'n

What is C ? (Optional?)

If we had $\begin{cases} x = 3\cos t \\ y = 3\sin t \end{cases} \Rightarrow x^2 + y^2 = 9$



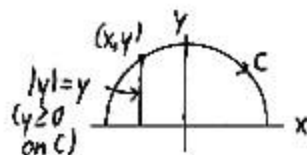
Here, $\begin{cases} x = -3\cos t \\ y = 3\sin t \end{cases}$



Good: No overlapping.

What is $\delta(x,y)$?

$\delta(x,y) = ky$

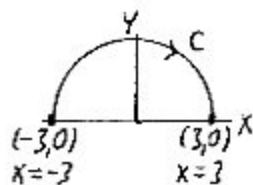


What is m ?

$$\begin{aligned}
 m &= \int_C \delta(x,y) ds \\
 &= \int_0^\pi ky \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \\
 &= \int_0^\pi k(3\sin t) \sqrt{(3\sin t)^2 + (3\cos t)^2} dt \quad \left. \begin{array}{l} x = -3\cos t, y = 3\sin t \\ \frac{dx}{dt} = 3\sin t, \frac{dy}{dt} = 3\cos t \end{array} \right\} \\
 &= \int_0^\pi k(3\sin t) \sqrt{9\sin^2 t + 9\cos^2 t} dt = \int_0^\pi k(3\sin t) \sqrt{9} dt = \int_0^\pi 9k \sin t dt \\
 &= 9k [-\cos t]_0^\pi \\
 &= 9k (-\cos \pi - (-\cos 0)) \\
 &= \boxed{18k} \underbrace{(-1)}_1 - \underbrace{(-1)}_{(-1)}
 \end{aligned}$$

If C lies on the graph of $y=f(x)$; $a \leq x \leq b \Rightarrow$
 let $x=t$, $y=f(t)$; $a \leq t \leq b$. (Similarly for $x=f(y)$.)

Redo Previous Ex (SKIPPED IN CLASS?)



$$y = \sqrt{9-x^2}, \quad -3 \leq x \leq 3$$

$$\begin{aligned} x=t, \quad y &= \sqrt{9-t^2} \text{ or } (9-t^2)^{1/2} \\ \frac{dx}{dt} &= 1, \quad \frac{dy}{dt} = \frac{1}{2}(9-t^2)^{-1/2}(-2t) \\ &= -\frac{t}{\sqrt{9-t^2}} \\ &\quad -3 \leq t \leq 3 \quad (t: -3 \rightarrow 3) \end{aligned}$$

$$\begin{aligned} m &= \int_C \delta(x,y) \, ds \\ &= \int_{-3}^3 ky \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} \, dt \end{aligned}$$

or $2 \int_0^3$ by sym. of C , $\delta(x,y)=ky$ even in x
 about $x=0$

(We basically
 could have
 used dx .)

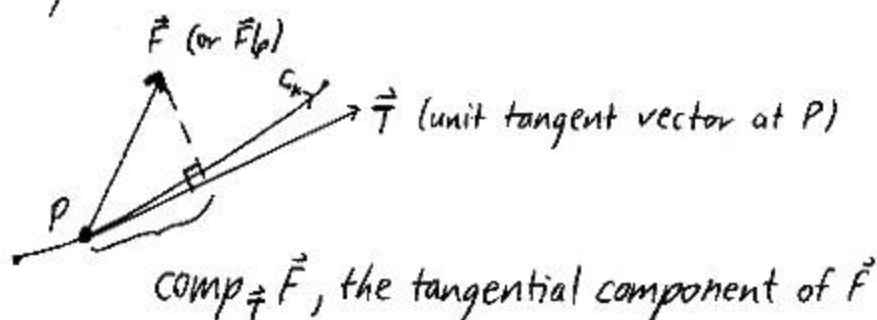
$$\begin{aligned} &= 2 \int_0^3 k \sqrt{9-t^2} \sqrt{(1)^2 + \left(-\frac{t}{\sqrt{9-t^2}}\right)^2} \, dt \\ &= 2 \int_0^3 k \sqrt{9-t^2} \sqrt{1 + \frac{t^2}{9-t^2}} \, dt \\ &= 2 \int_0^3 k \sqrt{(9-t^2)(1 + \frac{t^2}{9-t^2})} \, dt \\ &= 2 \int_0^3 k \sqrt{9-t^2+t^2} \, dt \\ &= 2 \int_0^3 3k \, dt \\ &= 6k \int_0^3 dt \\ &= 6k [t]_0^3 \\ &= 6k(3) \\ &= \boxed{18k} \end{aligned}$$

⑤ Line S of a Vector field, \vec{F}

Let W = the work done by \vec{F} on a particle moving along C [in the direction of orientation].

C_k , a tiny arc on C :

Normal component has no impact on the particle



$= \pm$ magnitude of force acting in the direction of \vec{T}

$$= \frac{\vec{F} \cdot \vec{T}}{\|\vec{T}\|}$$

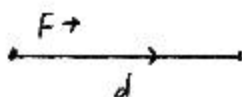
$$= \vec{F} \cdot \vec{T}$$

This depends on \vec{F} and C , but not the particle's speed along C .

(We're measuring the impact that \vec{F} has on the particle as it moves along C .)

Recall Calc II

If F is a constant scalar force, then $W = Fd$ here:



Now C curvy, \vec{F} nonconstant

On tiny C_k , $\vec{F} \cdot \vec{T} \approx \text{constant}$.

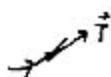
Work done along $C_k \approx \underbrace{(\vec{F} \cdot \vec{T})}_{\substack{\text{"force"} \\ \text{"impact"}}} \underbrace{\Delta s_k}_{\substack{\text{arc length} \\ \text{of } C_k}}$

$$W = \int_C \vec{F} \cdot \vec{T} \, ds$$

scalar function: special case of $f(x, y)$

Note $\int_C \vec{F} \cdot \vec{T} \, ds = \ominus \int_{-C} \vec{F} \cdot \vec{T} \, ds$
↑
 actually - (old \vec{T})

Stewart
 Sec. 6.1, 1070



Orientation matters!
 Speed along C
 still doesn't.

$$= \int_C \vec{F} \cdot \underbrace{\frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}}_{=\vec{T}(t)} \underbrace{\|\vec{r}'(t)\| \, dt}_{=ds}$$

← if $t \rightarrow$, but formula still OK if $t \rightarrow$ (!!!)
 (see review notes)

$$W = \int_C \vec{F} \cdot \vec{r}'(t) \, dt$$

$$= \frac{d\vec{r}}{dt} dt$$

$$= "d\vec{r}"$$

Maybe best form if \vec{F}, \vec{r} given
 in terms of t . (\vec{F} only known
 for points along C . ~~???~~)

$$W = \int_C \vec{F} \cdot d\vec{r}$$

Think: $\langle dx, dy \rangle$
 $= \langle M(x, y), N(x, y) \rangle$, cont. in a region containing C

$$W = \int_C M \, dx + N \, dy$$

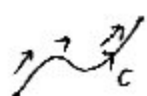
() often omitted

Differential Form

We'll use this a lot!

$$\text{In 3D, } W = \int_C M \, dx + N \, dy + P \, dz$$

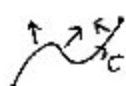
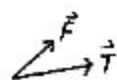
if $\vec{F}(x, y, z) = \langle M(x, y, z), N(x, y, z), P(x, y, z) \rangle$

Idea

$$W \gg 0$$

The force is with you!

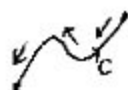
$$\vec{F} \cdot \vec{T} > 0$$



$$W = 0$$

No help/harm.

$$\vec{F} \cdot \vec{T} = 0$$



$$W \ll 0$$

Forces conspiring against you!

$$\vec{F} \cdot \vec{T} < 0$$



Work 6.6
Also: ft.-lbs.

Units If \vec{F} lengths in Newtons, $\begin{matrix} y \text{ (meters)} \\ \text{---} x \text{ (meters)} \end{matrix}$

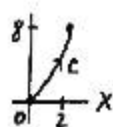
$\Rightarrow W$ in Newton-meters, or joules (J)

1 joule is the force needed to
accelerate a 1 kg mass by $1 \frac{m}{sec^2}$.

Like #4

$$\text{Ex } \vec{F}(x,y) = \underbrace{\langle y, \rangle}_{M(x,y)} \underbrace{\langle x+y, \rangle}_{N(x,y)}$$

C is the graph of $y = x^2 + 2x$ directed from $(0,0)$ to $(2,8)$.
Find the work, W , done by \vec{F} on a particle moving along C .

Sol'nDraw C (Optional?)

$$C: y = \underbrace{x^2 + 2x}_{f(x)}; \quad x: 0 \rightarrow 2 \quad (x \text{ is our parameter.})$$

(Also nice: $x = f(y)$; $y: a \rightarrow b$)

Use Differential Form:

$$\begin{aligned} W &= \int_C M dx + N dy \\ &= \int_C y dx + (x+y) dy \end{aligned}$$

$$\left. \begin{aligned} y &= x^2 + 2x \\ dy &= (2x + 2) dx \end{aligned} \right\} \begin{aligned} &\left(\begin{array}{l} \text{Write } x = \dots \text{ if } x = f(y) \\ dx = \dots \end{array} \right) \end{aligned}$$

$$= \int_0^2 \underbrace{(x^2 + 2x)}_y dx + \underbrace{[x + (x^2 + 2x)]}_{\underbrace{y}} \underbrace{(2x + 2)}_{dy} dx$$

$$= \int_0^2 [x^2 + 2x + (x^2 + 3x)(2x + 2)] dx$$

⋮

$$= \boxed{48}$$

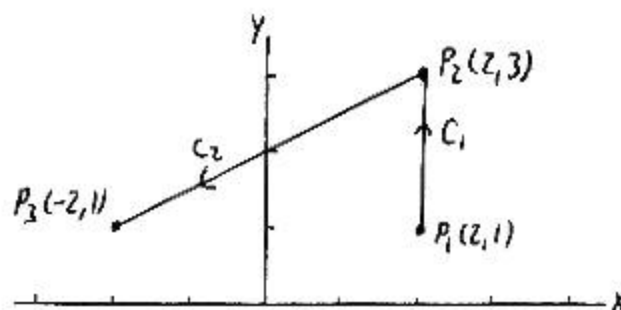
Note: If $\nabla \cdot \vec{F} < 0$, then $x: 2 \rightarrow 0$, and $W = \int_2^0 \dots = \boxed{-48}$. Makes sense!

OK if $x \downarrow$ in direction of motion.

\vec{F} hurts us commensurately
w/ how it helped us before.

Ex $\vec{F}(x,y) = \langle xy^2, e^{2y} \rangle$.

$C = C_1 \cup C_2$:



Find W .

Method 1 (Know both methods!): Use t as a parameter.

① Parameterize C_1, C_2

① $C_1: \begin{cases} x=2 \\ y=t \end{cases} \Rightarrow \begin{cases} dx=0 \\ dy=dt \end{cases}$

$t: 1 \rightarrow 3$

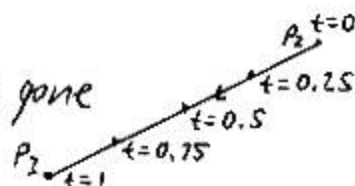
② Initial Point: $P_2(2,3)$
Displacement Vector: $\vec{P_2P_3} = \langle -2-2, 1-3 \rangle$
 $= \langle -4, -2 \rangle$

$C_2: \begin{cases} x=2-4t \\ y=3-2t \end{cases} \Rightarrow \begin{cases} dx=-4dt \\ dy=-2dt \end{cases}$

$t: 0 \rightarrow 1$

$\downarrow \quad \quad \downarrow$
 $P_2 \quad \quad P_3$

t = fraction of the way you've gone
from P_2 to P_3



(b) Find W

$$\begin{aligned}
 W &= \int_{C_1} M dx + N dy + \int_{C_2} M dx + N dy \\
 &= \int_{C_1} xy^2 dx + e^{2y} dy + \int_{C_2} xy^2 dx + e^{2y} dy \\
 &= \int_1^3 \underbrace{(2)(t)^2(0)}_{=0} + e^{2(t)} dt \\
 &\quad + \int_0^1 (2-4t)(3-2t)^2(-4) dt + e^{2(3-2t)}(-2) dt \\
 &\approx 198 - 209 \\
 &= \boxed{-11}
 \end{aligned}$$

Method 2: Use x and/or y as parameters.

$$\textcircled{C_1} \quad C_1: \begin{array}{l} x=2 \\ y: 1 \rightarrow 3 \end{array} \Rightarrow dx=0$$

$$\begin{aligned}
 \textcircled{C_2} \quad &\text{Point: } (2, 3) \\
 &\text{Slope} = \frac{1-3}{-2-2} = \frac{1}{2} \\
 &\text{Pt.-Slope form: } y-3 = \frac{1}{2}(x-2) \\
 &\Rightarrow \text{Slope-Int. form: } y = \frac{1}{2}x + 2
 \end{aligned}$$

$$\begin{aligned}
 C_2: \quad &x: 2 \rightarrow -2 \\
 &y = \frac{1}{2}x + 2 \Rightarrow dy = \frac{1}{2}dx
 \end{aligned}$$

$$\begin{aligned}
 W &= \int_{C_1} M dx + N dy + \int_{C_2} M dx + N dy \\
 &= \int_{C_1} xy^2 dx + e^{2y} dy + \int_{C_2} xy^2 dx + e^{2y} dy \\
 &= \int_1^3 \underbrace{(2)y^2(0)}_{=0} + e^{2y} dy + \int_2^{-2} \underbrace{x(\frac{1}{2}x+2)^2}_{x\text{-values}} dx + e^{2(\frac{1}{2}x+2)} \cdot \frac{1}{2} dx \\
 &\approx \boxed{-11}; \text{ same as for Method 1}
 \end{aligned}$$

18.3: INDEPENDENCE OF PATH (IP)

(A) Assumptions

C is ps.

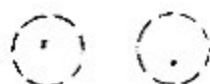
D is a simply connected open region containing C .

Don't
need
until
(E)

excludes boundary

"in one piece":
(any pair of points in D
can be joined by a ps
curve in D)

NO



No Michigans

In \mathbb{R}^3 , can
have finite #
of exceptional
pts. where
 \vec{F} , f undef.
for some of
our Thms.

D has no holes (if in \mathbb{R}^2).

i.e., No simple closed curve in D encloses points not in D .

$\vec{r}(a) = \vec{r}(b)$, and
the only self-intersection
point is there.

NO



Simply
connected
 D s in \mathbb{R}^2
discussed
in 18.7
(pp. 1017-8).
We'll extend
(E) into 3D
then, anyway.

\vec{F} is cont. in D .

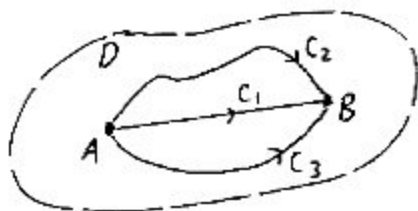
⑧ Indep of Path (IP)

Find $\int_C \vec{F} \cdot d\vec{r}$.

What if C is hard to parameterize? \leadsto
Can we use \rightarrow , instead?

We have indep. of path ^(IP) for \vec{F} in $D \iff$

For any pair of points A and B in D ,
 $\int_C \vec{F} \cdot d\vec{r}$ yields the same #, regardless
of which ps curve C in D from A to B
we use.



We can then say: $\int_A^B \vec{F} \cdot d\vec{r}$.

© Showing Indep. of Path for \vec{F} in D by
Finding a Potential Function, f

In D :

$$\int_C \vec{F} \cdot d\vec{r} \text{ is indep. of path } \iff \vec{F} \text{ is conservative} \\ \iff \vec{F} = \nabla f \text{ for some scalar potential func., } f$$

Proof pp. 982-4

Note: D need not be simply connected.
Need

(Note) that exists throughout D , though, in \mathbb{R}^3 , we may have a finite # of exceptional pts. where \vec{F}, f undefined. See 18.3.9 for an Ex in \mathbb{R}^2 where a suspected f doesn't work out.

Like #4

Ex $\vec{F}(x,y) = \langle 2xe^{2y} + 4y^3, 2x^2e^{2y} + 12xy^2 - 2y \rangle$.
Show that $\int_C \vec{F} \cdot d\vec{r}$ is indep. of path throughout \mathbb{R}^2 .

Sol'n

Find a potential, f , such that

$$\nabla f = \vec{F} \\ \langle f_x(x,y), f_y(x,y) \rangle = \langle 2xe^{2y} + 4y^3, 2x^2e^{2y} + 12xy^2 - 2y \rangle$$

Partially $\int f_x$ wrt x $f_x \uparrow f$ (Could $f \leftarrow f_y$ wrt y)

$$\int f_x(x,y) dx = \int (2xe^{2y} + 4y^3) dx$$

$$f(x,y) = 2e^{2y} \left(\frac{x^2}{2} \right) + 4y^3 x + \underbrace{g(y)}_{D_x[g(y)] = 0}$$

$$f(x,y) = x^2 e^{2y} + 4xy^3 + g(y)$$

D_y both sides $f \rightarrow f_y$

$$\begin{aligned}
 f_y(x,y) &= D_y [x^2 e^{2y} + 4xy^3 + g(y)] \\
 &= x^2 (2e^{2y}) + 4x(3y^2) + g'(y) \\
 &= 2x^2 e^{2y} + 12xy^2 + \textcircled{g'(y)}
 \end{aligned}$$

Compare with \textcircled{A} $\Rightarrow f_y(x,y) = 2x^2 e^{2y} + 12xy^2 - \textcircled{2y}$
 \textcircled{AA}

 $\int \textcircled{AA}$ wrt y to get $g(y)$

$$\int g'(y) dy = \int -2y dy$$

$$g(y) = -y^2 + K$$

\textcircled{C} already used

Write out $f(x,y)$ Use \textcircled{AAA} .In fact, this =
 $\int f_y(x,y) dy$

$$f(x,y) = x^2 e^{2y} + 4xy^3 - y^2 + K$$

Can D_x, D_y to \checkmark .Only Larson,
as far as I
knowAlternative Method (Don't use, though)

$$\begin{aligned}
 \int f_x(x,y) dy &= \dots = x^2 e^{2y} + 4xy^3 + g(y) \\
 \int f_y(x,y) dy &= \dots = x^2 e^{2y} + 4xy^3 - y^2 + h(x)
 \end{aligned}$$

Form a guess: $f(x,y) = x^2 e^{2y} + 4xy^3 - y^2 + K$
 D_x, D_y to \checkmark .

Ex Find a potential, f , for $\vec{F}(x,y,z) = \langle \underbrace{8x}_{f_x}, \underbrace{-9z}_{f_y}, \underbrace{-9y+3z^2}_{f_z} \rangle$.

Sol'n

$$f_x: 8x$$

$$f: \int 8x \, dx = 4x^2 + \underbrace{g(y,z)}$$

could have y, z , both, or neither

$$\begin{array}{l} f_y: \\ f_y: -9z \end{array} \quad \begin{array}{l} g_y(y,z) \\ \Downarrow \\ g_y(y,z) = -9z \\ g(y,z) = \int -9z \, dy \\ = -9zy + h(z) \end{array}$$

$$f: 4x^2 - 9yz + h(z) \quad (*)$$

$$\begin{array}{l} f_z: \\ f_z: -9y + 3z^2 \end{array} \quad \begin{array}{l} -9y + h'(z) \\ \Downarrow \\ -9y + h'(z) = -9y + 3z^2 \\ h'(z) = 3z^2 \\ h(z) = \int 3z^2 \, dz \\ h(z) = z^3 + K \end{array}$$

$$(*) \Rightarrow \boxed{f(x,y,z) = 4x^2 - 9yz + z^3 + K}$$

Alternative Method (Don't use!)

$$\left. \begin{array}{l} \int f_x(x,y,z) \, dx = 4x^2 + g(y,z) \\ \int f_y(x,y,z) \, dy = -9yz + h(x,z) \\ \int f_z(x,y,z) \, dz = -9yz + z^3 + \ell(x,y) \end{array} \right\} \Rightarrow \text{Guess: } f(x,y,z) = 4x^2 - 9yz + z^3 + K$$

D_x, D_y, D_z to \checkmark .

Stewart calls

① Fundamental Thm. for Line \int_C (FTLI) - extends FTC from Calc I



If \vec{F} is conservative in D with potential f ($\vec{F} = \nabla f$),
 then $\int_C \vec{F} \cdot d\vec{r} = \int_A^B \vec{F} \cdot d\vec{r}$ (by Indep.⁽¹⁾ of Path for \vec{F} in D)
 $= [f(x, y)]_A^B$ or $[f(x, y, z)]_A^B$
 $= f|_B - f|_A$

Physical Interpretation

The work done by a conservative force field \vec{F}
 along any path C from A to B

= The difference in potentials between A and B .

Doesn't
 matter
 where you
 start. If do
 1 full circuit
 \oint , same
 net effect,
 $\oint \vec{F} \cdot d\vec{r} = 0$

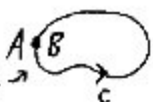
"Simple" helps.
 Orientation
 unclear for



Where do
 we go when
 we hit
 this pt.?

What if $A=B$?

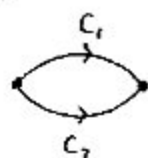
closed curve \rightarrow



$$\begin{aligned}\int_C \vec{F} \cdot d\vec{r} &= \int_A^A \vec{F} \cdot d\vec{r} \\ &= f|_A - f|_A \\ &= 0\end{aligned}$$

True "Converse":

If $\int_C \vec{F} \cdot d\vec{r} = 0$ for every simple closed curve C in D ,
 then \vec{F} is conservative, and we have indep. of path for \vec{F} in D .
 (IP)

Why?

$$\text{If } \int_C \vec{F} \cdot d\vec{r} = 0$$

$$\Rightarrow \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{-C_2} \vec{F} \cdot d\vec{r} = 0$$

$$\Rightarrow \int_{C_1} \vec{F} \cdot d\vec{r} - \int_{C_2} \vec{F} \cdot d\vec{r} = 0$$

$$\Rightarrow \int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot d\vec{r}$$

Ex From ©: $\vec{F}(x,y) = \langle 2xe^{2y} + 4y^3, 2x^2e^{2y} + 12xy^2 - 2y \rangle$.
 (*conservative in \mathbb{R}^2).

Evaluate $\int_{(1,2)}^{(3,4)} \vec{F} \cdot d\vec{r}$.Method 1: Use FTLI.

$$= [f(x,y)]_{(1,2)}^{(3,4)}$$


$$= [x^2e^{2y} + 4xy^3 - y^2]_{(1,2)}^{(3,4)} \quad \text{from ©}$$

↑
Don't need "+K."

$$= [(3)^2e^{2(4)} + 4(3)(4)^3 - (4)^2] \\ - [(1)^2e^{2(2)} + 4(1)(2)^3 - (2)^2]$$

$$= \boxed{9e^8 - e^4 + 724}$$

$$752 + 9e^8 \\ - [28 + e^4]$$

whether we 

Method 2: Use ©, 18.2 method for "easy" C .

(IP)
 (E) Showing Indep. of Path for \vec{F} in D (Method 2)

If $\vec{F} = \langle M, N \rangle$, and M, N have cont. 1st PDs \textcircled{A} on D ,
 and if D is simply connected, then
 'no holes'

$$\int_C \vec{F} \cdot d\vec{r} = \int M dx + N dy \text{ is indep. of path (IP)}$$

$$\iff \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y} \text{ for all } (x, y) \text{ in } D$$

Proof Idea

(\Rightarrow) IP \Rightarrow There exists f :

$$\vec{F}: \begin{array}{cc} \nearrow & \searrow \\ M & N \\ \nwarrow & \nearrow \\ M_y = N_x \end{array}$$

because $f_{xy} = f_{yx}$ it \textcircled{A}

(\Leftarrow) Hard! Requires that D be simply connected.

Ex from \textcircled{C} : $\vec{F}(x, y) = \langle \underbrace{2xe^{2y} + 4y^3}_{M(x, y)}, \underbrace{2x^2e^{2y} + 12xy^2 - 2y}_{N(x, y)} \rangle$
 Assume 1st PDs are cont. on \mathbb{R}^2 .

Show that $\int_C \vec{F} \cdot d\vec{r}$ is indep. of path (IP) throughout \mathbb{R}^2 .
 (In \textcircled{C} , we did this by finding a potential.)

Sol'n

$$\frac{\partial N}{\partial x} = 4xe^{2y} + 12y^2$$

for all (x, y) in \mathbb{R}^2

$$\begin{aligned} \frac{\partial M}{\partial y} &= 2x(2e^{2y}) + 12y^2 \\ &= 4xe^{2y} + 12y^2 \end{aligned}$$

$$\Rightarrow \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

$\Rightarrow \int_C \vec{F} \cdot d\vec{r}$ is IP throughout \mathbb{R}^2 .

If C in D ,
 here, $D = \mathbb{R}^2$.

Note: To compute $\int_{(1,2)}^{(3,4)} \vec{F} \cdot d\vec{r}$, we can use 18.2 on C \nearrow $(3,4)$ $\left(\begin{array}{l} x=1+2t \\ y=2+2t \\ t:0 \rightarrow 1 \end{array} \right)$

Note 1

C can't pass
over a "hole."

If $\frac{\partial N}{\partial x} \neq \frac{\partial M}{\partial y}$ at any (x,y) in D ,
then we do not have IP for \vec{F} in D .

Like #27
<, + >

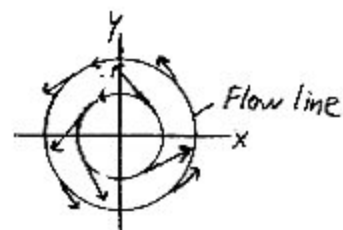
Note 2 (How to Ace the Rest of Calculus, pp. 234-5) (Skim in class)

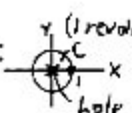
\vec{F} is an approx.
"kitchen
sink" field.
Vectors longer
as $\|z\|$
goes from
 $1 \rightarrow 0$

\vec{F} undef.
This is "approximately"
a sink, water
doesn't move in!

If $\vec{F}(x,y) = \left\langle \frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right\rangle$, then

$$\frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}, \text{ except at } (0,0).$$



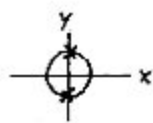
Turns out for:  No simply connected region D
contains C .

$$\int_C \vec{F} \cdot d\vec{r} = 2\pi \neq 0$$

↑
Using 18.2.

\vec{F} is not conservative on any region containing C .

If you attempt to construct a potential, f ,
you may get $-\tan^{-1}(\frac{y}{x})$, but observe
that this is undefined when $x=0$.

Note 3

In 18.7, we will extend \textcircled{E} to 3D.

(Typed in review:)

⑤ When is \vec{F} Conservative in \mathbb{R}^2 ? Equivalent Statements:

In a connected region D (in which \vec{F} is cont.)...
 "in one piece"

① \vec{F} is conservative
 (i.e., $\vec{F} = \nabla f$ for some scalar potential func. f)

② We have IP: $\int_C \vec{F} \cdot d\vec{r}$

③ $\int_C \vec{F} \cdot d\vec{r} = 0$ for every simple closed curve C in D

④a) $\frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$ throughout D

if $\vec{F} = \langle M, N \rangle$ is "nice."

Note: $\int_C \vec{F} \cdot d\vec{r} = \int_C M dx + N dy$

If we start with ④a), then we require
 that D be simply connected.
 no holes
 (in \mathbb{R}^2)

When we discuss the \mathbb{R}^3 case in 18.7, we will
 replace ④a) with ④b).

18.4: GREEN'S THEOREM

George Green (1793-1841) was an English mathematical physicist who published this theorem in an EM paper in 1828. Self-taught!

(A) Prelims

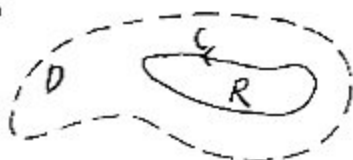
In \mathbb{R}^2 :

Let C be a ps simple closed curve that is the boundary of $R = C \cup \text{interior of } C$.

D is an open region containing R .

C is boundary of R : $C = \partial R$

(in \mathbb{R}^2)



Let $\vec{F} = \langle M, N \rangle$, where M, N are "nice" throughout D .

i.e., are cont. and have cont. 1st PDs

$$\oint_C \vec{F} \cdot d\vec{r}$$

along C once in the positive direction

R always on the left

counterclockwise unless hole; see (C)

\oint also used

② Green's Thm

Green's Thm. an extension of FTC.

$$\oint_C \vec{F} \cdot d\vec{r} = \oint_C M dx + N dy$$

$$= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

= 0 if \vec{F} is conservative throughout D
(not "if and only if"; could be 0 even if \vec{F} isn't)

Proof Note (FTC)

Fundamental Thm. of Calculus is used to equate a \iint involving partials with a " \oint " along a boundary.

③ Area of R

Note If you use $\vec{F}(x,y) = \langle -y, x \rangle$, then

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R (1 - (-1)) dA$$

$$= 2 \iint_R dA$$

$$= 2 (\text{Area of } R)$$

$$\Rightarrow \text{Area of } R = \frac{1}{2} \oint_C -y dx + x dy$$

Often easier to use than: $\text{Area} = \oint_C x dy$ or $\oint_C -y dx$

How to Ace: You can judge a book by its cover!

(Area of R)^C

Carson S², ET
1023

Try this: Show that the area of the ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ is πab . ($a > 0, b > 0$)

Hint: See my 13.1 Notes.

May be easier to remember:

$$\text{Area of } R = \frac{1}{2} \oint_C x dy - y dx$$

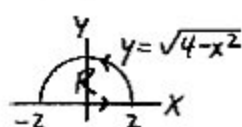
② Ex (#6)

Evaluate $\oint_C y^2 dx + x^2 dy$, where

C is the boundary of the region bounded by the semicircle $y = \sqrt{4-x^2}$ and the x -axis.

Sol'n

Draw C



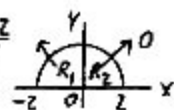
$$\begin{aligned} \oint_C y^2 dx + x^2 dy &= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \\ \underbrace{\quad}_{\substack{\text{Both nice} \\ M \quad N}} &= \iint_R (2x - 2y) dA \end{aligned}$$

In Cartesian coords,

$$= \int_{x=-2}^{x=2} \int_{y=0}^{y=\sqrt{4-x^2}} (2x - 2y) dy dx$$

NOT $\neq 2 \int_0^2$, because not even in x .


Turns out: $-\frac{32}{3}$



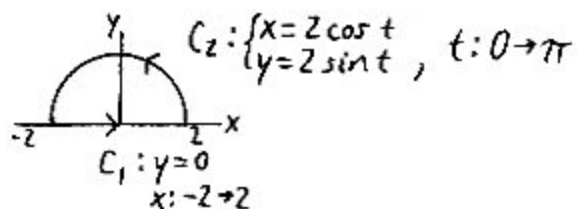
Not bad, but...

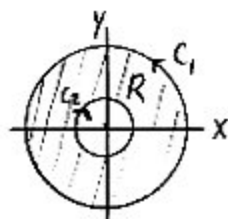
PCs easier!

$$\begin{aligned}
 \iint_R (2x - 2y) dA &= \int_{\theta=0}^{\theta=\pi} \int_{r=0}^{r=2} (2r\cos\theta - 2r\sin\theta) r dr d\theta \\
 &= 2 \int_{\theta=0}^{\theta=\pi} \int_{r=0}^{r=2} r(\cos\theta - \sin\theta) r dr d\theta \\
 &= 2 \left[\int_0^2 r^2 dr \right] \left[\int_0^\pi (\cos\theta - \sin\theta) d\theta \right] \\
 &= 2 \left(\left[\frac{r^3}{3} \right]_0^2 \right) \left([\sin\theta + \cos\theta]_0^\pi \right) \\
 &= 2 \left(\frac{8}{3} \right) \left(\underbrace{[\sin\pi + \cos\pi]}_{=0} - \underbrace{[\sin 0 + \cos 0]}_{=1} \right) \\
 &= \frac{16}{3} (-1 - 1) \\
 &= \boxed{-\frac{32}{3}}
 \end{aligned}$$

Note 1: If  $\Rightarrow \int_{C \text{ in neg. direction}} y^2 dx + x^2 dy = \frac{32}{3}$

Note 2: 18.2 Method longer



(E) Extension

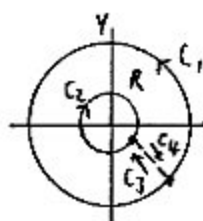
$$\oint_{C_1} \vec{F} \cdot d\vec{r} + \oint_{C_2} \vec{F} \cdot d\vec{r}$$

↓
R stays on left

$$= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \quad (\star)$$

Why?

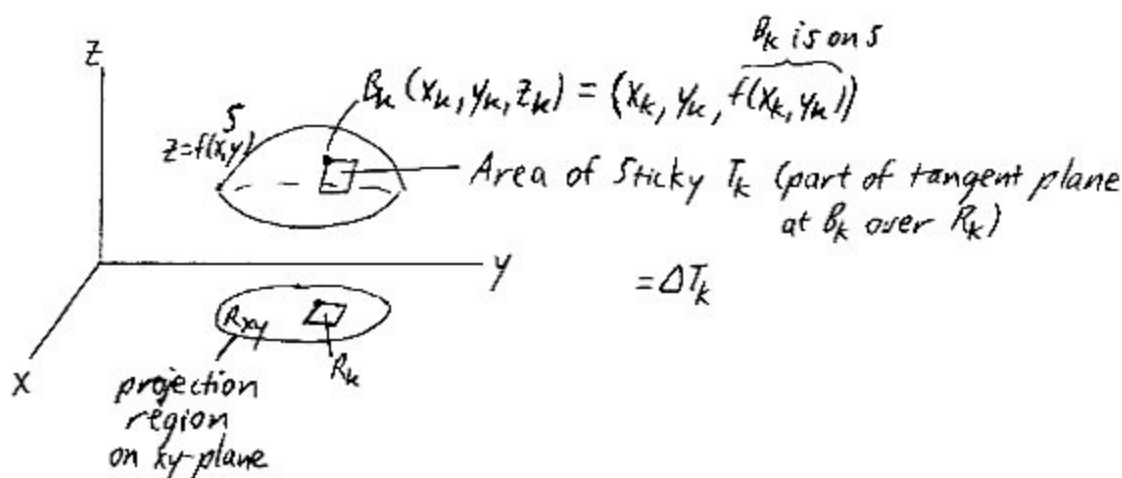
Make a slit.



$$(\star) = \oint_{C_1} \vec{F} \cdot d\vec{r} + \underbrace{\oint_{C_3} \vec{F} \cdot d\vec{r} + \oint_{C_2} \vec{F} \cdot d\vec{r} + \oint_{C_4} \vec{F} \cdot d\vec{r}}_{\text{Sum} = 0} \text{ by Green.}$$

18.5: SURFACE INTEGRALS

(A) Review Surface Area (17.4)



(Assume f is "nice" - cont. and has cont. 1st PDs on R_{xy} . If there is a problem at the boundary, we may need an improper integral.)

$$\begin{aligned} \text{Surface Area} &= \iint_S dS \\ &= \iint_{R_{xy}} \sqrt{1 + [f_x(x,y)]^2 + [f_y(x,y)]^2} dA \end{aligned}$$

Similar if $y = f(x, z)$; $x = f(y, z)$.

(B) Mass, m , of a Surface, S

$$\text{Mass of Sticky } T_k \approx \underbrace{\delta(x_k, y_k, f(x_k, y_k))}_{\substack{\text{Area mass density} \\ \text{at } B_k \text{ (}\approx \text{same} \\ \text{throughout sticky)} \\ \text{(Units like g/m}^2\text{)}}} \underbrace{\Delta T_k}_{\substack{\text{Area of} \\ \text{Sticky } T_k \\ \text{(Units like m}^2\text{)}}} \quad \leftarrow \textcircled{A}$$

$$\begin{aligned} m = \text{Mass of } S &= \lim_{\|P\| \rightarrow 0} \sum_k \textcircled{A} \\ &= \iint_S \delta(x, y, z) dS \\ &= \iint_{R_{xy}} \delta(x, y, f(x, y)) \sqrt{1 + [f_x(x, y)]^2 + [f_y(x, y)]^2} dA \end{aligned}$$

Ex (Like #1 - solutions manual flawed)

Find the mass of S , if $\delta(x,y,z) = x^2$, and S is the upper half of the sphere $x^2 + y^2 + z^2 = a^2$, ($a > 0$).

Sol'n

Rewrite the eq. for S in the form $z = f(x,y)$.

$$x^2 + y^2 + z^2 = a^2 \quad (a > 0)$$

$$z = \pm \sqrt{a^2 - x^2 - y^2}$$

↑ we take the upper half of the sphere

Find m

$$m = \iint_{R_{xy}} \delta \sqrt{1 + [f_x(x,y)]^2 + [f_y(x,y)]^2} dA$$

$$f(x,y) = \sqrt{a^2 - x^2 - y^2}$$

$$= (a^2 - x^2 - y^2)^{1/2}$$

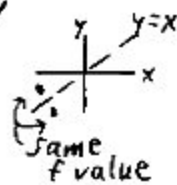
$$f_x(x,y) = \frac{1}{2} (a^2 - x^2 - y^2)^{-1/2} (-2x)$$

$$= -\frac{x}{\sqrt{a^2 - x^2 - y^2}}$$

$$[f_x(x,y)]^2 = \frac{x^2}{a^2 - x^2 - y^2}$$

$f(x,y)$ is symmetric in x and y
(i.e., $f(x,y) = f(y,x)$).

$$\Rightarrow [f_y(x,y)]^2 = \frac{y^2}{a^2 - y^2 - x^2}$$



$$m = \iint_{R_{xy}} x^2 \sqrt{1 + \frac{x^2}{a^2 - x^2 - y^2} + \frac{y^2}{a^2 - x^2 - y^2}} dA$$

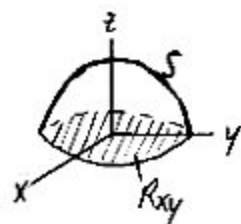
$$= \iint_{R_{xy}} x^2 \sqrt{1 + \frac{x^2 + y^2}{a^2 - x^2 - y^2}} dA$$

1 is how many fourths?

$$= \iint_{R_{xy}} x^2 \sqrt{\frac{a^2 - x^2 - y^2 + x^2 + y^2}{a^2 - x^2 - y^2}} dA$$

$$= \iint_{R_{xy}} x^2 \left(\frac{a}{\sqrt{a^2 - x^2 - y^2}} \right) dA$$

→ PCs



$$= \int_{\theta=0}^{2\pi} \int_{r=0}^a (r \cos \theta)^2 \left(\frac{a}{\sqrt{a^2 - r^2}} \right) r dr d\theta$$

$$= \int_{\theta=0}^{2\pi} \int_{r=0}^a r^2 \cos^2 \theta \left(\frac{a}{\sqrt{a^2 - r^2}} \right) r dr d\theta$$

$$= a \left[\int_0^{2\pi} \cos^2 \theta d\theta \right] \left[\int_0^a \frac{r^3}{\sqrt{a^2 - r^2}} dr \right]$$

$$\stackrel{\text{PRI}}{=} \int_0^{2\pi} \frac{1 + \cos(2\theta)}{2} d\theta$$

Improper \int !!

$$= \frac{1}{2} [\theta + \frac{1}{2} \sin(2\theta)]_0^{2\pi}$$

(Integrand is undefined at $r=a$.)

$$= \frac{1}{2} \left([2\pi + \frac{1}{2} \sin(4\pi)] - [0] \right)$$

$$= (\pi)$$

$$= \pi a \cdot \lim_{t \rightarrow a^-} \underbrace{\int_0^t \frac{r^3}{\sqrt{a^2 - r^2}} dr}_{\text{Work out Indefinite } \int, 1^{st}}$$

Work out Indefinite $\int, 1^{st}$.

Trig sub: $r = a \sin \delta$ (We've had θ) or

Fancy u -sub

$$\begin{aligned} u &= a^2 - r^2 & \Rightarrow & r^2 = a^2 - u \\ du &= -2r dr \\ \Rightarrow r dr &= -\frac{1}{2} du \end{aligned}$$

$$\int \frac{r^3}{\sqrt{a^2 - r^2}} dr = \int \frac{r^2 \cdot r}{\sqrt{a^2 - r^2}} dr$$

$$= \int \frac{(a^2 - u)(-\frac{1}{2} du)}{\sqrt{u}}$$

$$= -\frac{1}{2} \int (a^2 u^{-\frac{1}{2}} - u^{\frac{1}{2}}) du$$

$$= -\frac{1}{2} \left[a^2 \left(\frac{u^{1/2}}{1/2} \right) - \frac{u^{3/2}}{3/2} \right] + C$$

$$= -\frac{1}{2} \left[2a^2 \sqrt{u} - \frac{2}{3} u^{3/2} \right] + C$$

$$= -a^2 \sqrt{a^2 - r^2} + \frac{1}{3} (a^2 - r^2)^{3/2} + C$$

$$= \pi a \cdot \lim_{t \rightarrow a^-} \left[-a^2 \sqrt{a^2 - r^2} + \frac{1}{3} (a^2 - r^2)^{3/2} \right]_0^t$$

$$= \pi a \cdot \lim_{t \rightarrow a^-} \left(\underbrace{\left[-a^2 \sqrt{a^2 - t^2} + \frac{1}{3} (a^2 - t^2)^{3/2} \right]}_{\rightarrow 0} - \underbrace{\left[-a^2 \sqrt{a^2} + \frac{1}{3} (a^2)^{3/2} \right]}_{\substack{= -a^2 \sqrt{a^2} \\ = -a^3}} \right)$$

$$= \pi a \left(a^3 - \frac{1}{3} a^3 \right)$$

$$= \pi a \left(\frac{2}{3} a^3 \right)$$

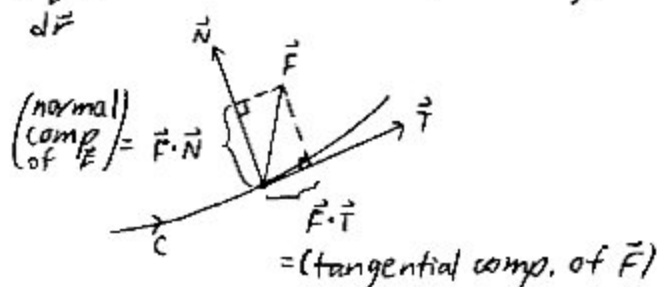
$$= \boxed{\frac{2\pi a^4}{3}}$$

In upper
division
physics

© Flux Integrals

18.2: 2D/3D

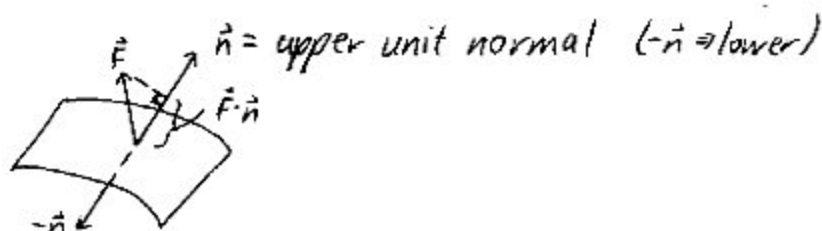
$$\int_C \vec{F} \cdot \underbrace{\vec{T}}_{d\vec{r}} ds = \text{Work done by } \vec{F} \text{ along } C.$$



Now: 2D

$$\int_C \vec{F} \cdot \vec{N} ds = \text{Flux (Latin for "flow") of } \vec{F} \text{ across } C.$$

Now: 3D



$$\iint_S \underbrace{\vec{F} \cdot \vec{n}}_{d\vec{S}} dS = \text{Flux of } \vec{F} \text{ across } S.$$

Work-Recall:
 $d\vec{r} = \vec{T} ds$
Flux-Now:
 $d\vec{S} = \vec{n} dS$

Sample units: $\iint \underbrace{\left\langle \frac{m}{\text{sec}}, \frac{m}{\text{sec}}, \frac{m}{\text{sec}} \right\rangle \cdot \underbrace{\vec{n}}_{\text{(no units)}}}_{\left(\frac{m}{\text{sec}} \right)} dS$

$\underbrace{\left(\frac{m^3}{\text{sec}} \right)}_{\text{Volume}}$

Volume
time : flow rate across S $\left(\frac{m^3}{\text{sec}} \right)$

Let S be the graph of $z = f(x, y)$. What's \vec{n} ?

$$\underbrace{z - f(x, y)}_{\text{"}g(x, y, z)\text{"}} = 0$$

$\Rightarrow S$ is a level surface of g .

$\Rightarrow \vec{\nabla} g \perp S$

\Rightarrow We use

$$\vec{n} = \frac{\vec{\nabla} g}{\|\vec{\nabla} g\|}$$

as our upper unit normal to S

$$= \frac{\langle \frac{\partial g}{\partial x}, \frac{\partial g}{\partial y}, \frac{\partial g}{\partial z} \rangle}{\|\vec{\nabla} g\|}$$

$$= \frac{\langle -f_x, -f_y, 1 \rangle}{\sqrt{1 + (f_x)^2 + (f_y)^2}}$$

$$\underbrace{z - f(x, y)}_{g(x, y, z)} = 0$$

Book does \rightarrow

$$\begin{aligned} \iint_S \vec{F} \cdot \vec{n} \, dS &= \iint_{R_{xy}} \vec{F} \cdot \frac{\langle -f_x, -f_y, 1 \rangle}{\sqrt{1 + (f_x)^2 + (f_y)^2}} \sqrt{1 + (f_x)^2 + (f_y)^2} \, dA \\ &= \iint_{R_{xy}} \vec{F} \cdot \vec{\nabla} g \, dA \end{aligned}$$

Ex Find the flux of \vec{F} across S , where
 $\vec{F}(x,y,z) = \langle z, 2, y \rangle$, and
 S is the first-octant portion of the plane

$$z = -4x - 8y + 8.$$

Sol'n

$$\underbrace{z + 4x + 8y - 8}_{g(x,y,z)} = 0$$

$$\vec{\nabla} g(x,y,z) = \langle 4, 8, 1 \rangle \quad (\text{This is a normal vector to this plane; see Ch. 14 (14.5).})$$

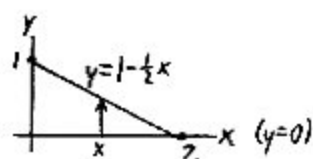
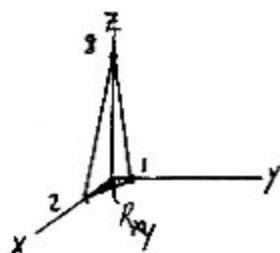
$$\begin{aligned} \text{Flux} &= \iint_{R_{xy}} \vec{F} \cdot \vec{\nabla} g \, dA \\ &= \iint_{R_{xy}} \langle z, 2, y \rangle \cdot \langle 4, 8, 1 \rangle \, dA \\ &= \iint_{R_{xy}} (4z + 16 + y) \, dA \\ &\quad \text{write out in terms of } x, y \\ &= \iint_{R_{xy}} [4(-4x - 8y + 8) + 16 + y] \, dA \\ &= \iint_{R_{xy}} [-16x - 31y + 48] \, dA \end{aligned}$$

What is R_{xy} ?

$$z = -4x - 8y + 8 \quad \text{in Octant I}$$

$$4x + 8y + z = 8$$

Intercept Method for Graphing a Plane



Intercept Form:

$$\frac{x}{2} + \frac{y}{1} = 1$$

$$y = 1 - \frac{1}{2}x$$

$$\text{Flux} = \int_{x=0}^{x=2} \int_{y=0}^{y=1-\frac{1}{2}x} [-16x - 31y + 48] dy dx$$

$$\vdots$$

$$= \boxed{27}$$

Units: maybe $\frac{m^3}{sec}$?

Note 1: We require that \vec{n} be continuous over S , except on the boundary (i.e., S is orientable).

Note 2: We assume S has 2 sides (here: top/bottom).
The Möbius strip is 1-sided and is not orientable.
see p.1003

We can parameterize such a surface:

$$\vec{r}(u, v) = \langle (4 - v \sin u) \cos(2u), \\ (4 - v \sin u) \sin(2u), \\ v \cos u \rangle$$

$$0 \leq u \leq \pi, \quad -1 \leq v \leq 1$$

Note 3: If S is closed, we have outer and inner normals.



$$\text{Assume: } \text{outer } \vec{n} \Rightarrow \text{Flux} = \iint_S \vec{F} \cdot \vec{n} \, dS$$

= net outward flow across S

If $> 0 \Rightarrow$ There's a source of \vec{F} within S .

If $< 0 \Rightarrow$ sink

If $= 0 \Rightarrow$ neither

$$\text{Flux}(\text{upper}) + \text{Flux}(\text{lower})$$

A general advanced method can employ spherical coords. directly.

(or GAUSS'S)

18.6: DIVERGENCE THEOREM

discovered via electrostatics

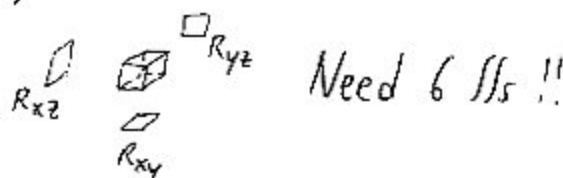
also named after Carl Gauss (German mathem.!!, 1777-1855)

Michel Ostrogradsky (Russian mathem., 1801-61)

Carson 6ed - 1050

Often better than 18.5 for closed surfaces!

In 18.5,

Let S be a closed surface bounding a 3D region, Q .Let \vec{n} be the unit outer normal.Let \vec{F} have cont. PDs on Q .

Then,

$$\underbrace{\iint_S \vec{F} \cdot \vec{n} \, dS}_{\text{Flux of } \vec{F} \text{ across } S} = \iiint_Q (\text{div } \vec{F}) \, dV$$

Sample Units for Right-Hand Side
(18.5.5 for Left)

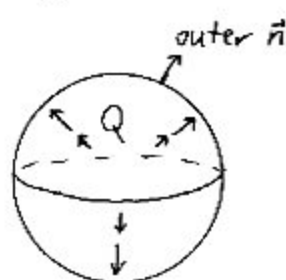
$$\underbrace{\iiint}_{\text{continuous addition}} \underbrace{\text{div } \vec{F}}_{\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}} \, dV$$

$(\frac{m}{sec} + \dots)$ (m^3)
 $(\frac{m}{sec})$ (m^3)
 $(\frac{m^3}{sec})$

Note 1: (20) Flux = $\oint_C \vec{F} \cdot \vec{N} \, ds = \iint_R (\text{div } \vec{F}) \, dA$ \textcircled{R}

↑
by Green's Thm.

Note 2:

 \vec{F} vectorsHere, $\text{div } \vec{F} > 0$ throughout Q \Rightarrow Flux across $S > 0$ \Rightarrow source in Q

Actually, the
idea of
 $(\text{div } \vec{F})_p$
comes
from
18.6.

Ex (#8)

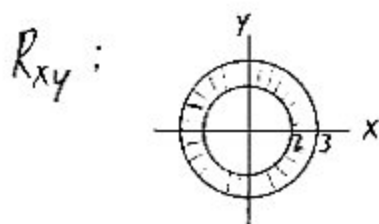
Find the flux of $\vec{F}(x,y,z) = \langle xy^2, yz^2, zx^2 \rangle$ through S , where S is the surface of the region between the cylinders $x^2 + y^2 = 4$ and $x^2 + y^2 = 9$ and between the planes $z = -1$ and $z = 2$.

Sol'n

$$\begin{aligned}\text{Flux} &= \iint_S \vec{F} \cdot \vec{n} \, dS \\ &= \iiint_Q (\text{div } \vec{F}) \, dV\end{aligned}$$

$$\begin{aligned}\text{div } \vec{F} &= \frac{\partial}{\partial x}(xy^2) + \frac{\partial}{\partial y}(yz^2) + \frac{\partial}{\partial z}(zx^2) \\ &= y^2 + z^2 + x^2 \\ &= \underbrace{x^2 + y^2 + z^2}_{=r^2 \text{ in Cyl. Coords.}} \\ &= r^2 + z^2\end{aligned}$$

$$= \iiint_Q (r^2 + z^2) r \, dr \, d\theta \, dz$$



Note
S:

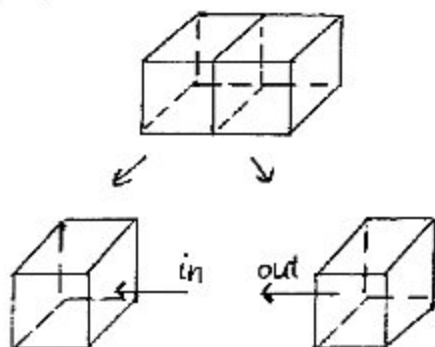


$$\begin{aligned}
 & \swarrow \text{R}_{xy} \searrow \\
 &= \int_{\theta=0}^{\theta=2\pi} \int_{r=2}^{r=3} \left[\int_{z=-1}^{z=2} (r^2 + z^2) r \, dz \right] dr \, d\theta \\
 &= \int_{z=-1}^{z=2} (r^3 + rz^2) \, dz \\
 &= \left[r^3 z + r \left(\frac{z^3}{3} \right) \right]_{z=-1}^{z=2} \\
 &= \left(\left[2r^3 + \frac{8}{3}r \right] - \left[-r^3 - \frac{1}{3}r \right] \right) \\
 &= (3r^3 + 3r) \\
 &= 3(r^3 + r)
 \end{aligned}$$

$$\begin{aligned}
 &= \left[\int_0^{2\pi} d\theta \right] \left[\int_2^3 3(r^3 + r) \, dr \right] \\
 &= 2\pi \left[3 \left(\frac{r^4}{4} + \frac{r^2}{2} \right) \right]_2^3 \\
 &= 6\pi \left(\left[\frac{81}{4} + \frac{9}{2} \right] - \underbrace{\left[4 + 2 \right]}_{=6} \right) \\
 &= 6\pi \left(\frac{81 + 18 - 24}{4} \right) \\
 &= 6\pi \left(\frac{75}{4} \right) \\
 &= \boxed{\frac{225\pi}{2}} \text{ (flux units)}
 \end{aligned}$$

Why Does the Theorem Work?

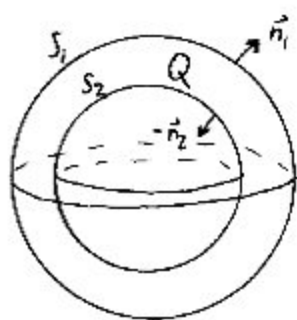
Roughly break Q into cubes.



Again, FTC
idea here -
boundary!!
Same flavor
as Green, Stokes,
FTLI.
Larson (ed) →
1054

The only net change of flow throughout Q
will be at the boundary, S ,
again, FTC idea here

Extension



$$\begin{aligned} & \iiint_Q (\operatorname{div} \vec{F}) dV \\ &= \iint_{S_1} \vec{F} \cdot \vec{n}_1 dS + \iint_{S_2} \vec{F} \cdot (-\vec{n}_2) dS \end{aligned}$$

Stewart 1137
5th ed 67
Used Thm. to
prove
Archimedes's
principle

18.7: STOKES'S THEOREM ("Green in 3D")

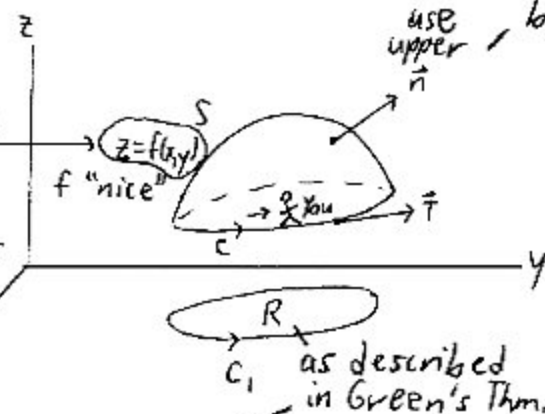
Stewart 1126
5ed ET

published in 1854 by George Stokes (Irish Eng. mathem. physicist, 1819-1903).
Lord Kelvin also key in both thms.; wrote letter to Stokes in 1850.

Broadly:
Orientation, \vec{n}
consistent
w/ right-hand-
rule idea.

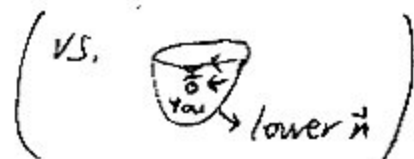
R is "Greentype"
 C_1 is simple
closed curve
 $R = C_1$ interior
of C_1

We will
focus on
this
special
case;
Stokes is
more
general.



use
upper
 \vec{n}

because you must walk on top
of C in the indicated direction
in order to keep S to your left.
This direction gives the positive
orientation of C .



(See 18.5.6.)

$$\text{Work} = \oint_C \vec{F} \cdot \vec{T} \, ds = \iint_S (\text{curl } \vec{F}) \cdot \vec{n} \, dS = \iint_{R_{xy}} (\text{curl } \vec{F}) \cdot \vec{\nabla} g \, dA$$

Assume \vec{F} is
"nice" in an
open region
containing S .

= rotation of \vec{F} about \vec{n}
= $\text{rot } \vec{F}$

where
 $g(x, y, z) = z - f(x, y)$

= Flux of $\text{curl } \vec{F}$ across S
= Surface \iint of normal component
of $\text{curl } \vec{F}$ over S .

Other books:
 $\text{rot } \vec{F} = \text{curl } \vec{F}$

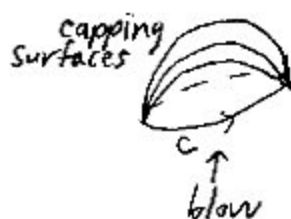
Stokowski →

Green's
and Stokes's
Thms. are
extensions
of FTC.
So is Div. Thm.

This is the 3D extension of Green's Thm., which can
be expressed as: $\oint_C \vec{F} \cdot \vec{T} \, ds = \iint_R (\text{curl } \vec{F}) \cdot \vec{k} \, dA$
in "vector form."

$\langle \cdot, \cdot \rangle$
Insert
Given in \mathbb{R}^2

Observe: If you think of "blowing a bubble" through C ,
you get the same value for the work integral!!



if $z = f(x, y)$ where f is "nice";
otherwise, more complicated
story...

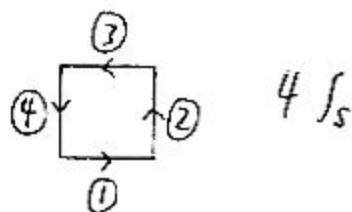
Term by
Schey:
3ed, 92

Stokes explains "paddlewheel" interpretation for $\vec{\text{curl}}$. (18.1.5) 18.7.2

Ex (#6)

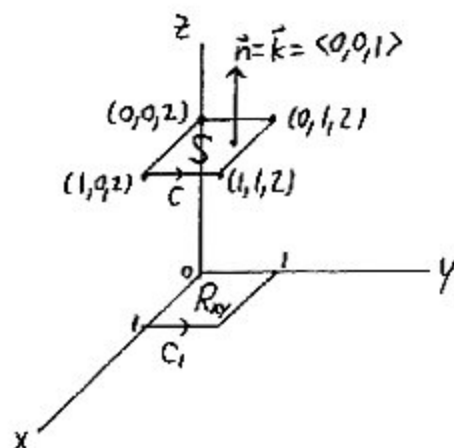
If $\vec{F}(x,y,z) = \langle yz, xy, xz \rangle$, and C is the square with vertices $(0,0,2)$, $(1,0,2)$, $(1,1,2)$, and $(0,1,2)$, use Stokes' theorem to evaluate $\oint_C \vec{F} \cdot d\vec{r}$.

Without Stokes



With Stokes

$$\begin{aligned}\vec{\text{curl}} \vec{F} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & xy & xz \end{vmatrix} \\ &= \langle \frac{\partial}{\partial y}(xz) - \frac{\partial}{\partial z}(xy), -[\frac{\partial}{\partial x}(xz) - \frac{\partial}{\partial z}(yz)], \frac{\partial}{\partial x}(xy) - \frac{\partial}{\partial y}(xz) \rangle \\ &= \langle 0 - 0, -[z - y], y - z \rangle \\ &= \langle 0, y - z, y - z \rangle\end{aligned}$$



S lies on the graph of $z=2$.

$$\underbrace{z-2}_{g(x,y,z)} = 0$$

$$\vec{\nabla} g(x,y,z) = \langle 0, 0, 1 \rangle (= \vec{k})$$

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_{R_{xy}} (\text{curl } \vec{F}) \cdot \vec{\nabla} g \, dA$$

$$= \iint_{R_{xy}} \langle 0, y-z, y-z \rangle \cdot \langle 0, 0, 1 \rangle \, dA$$

$$= \iint_{R_{xy}} (y-z) \, dA$$

\uparrow
 $z=2$

$$= \int_0^1 \int_0^1 (y-2) \, dx \, dy$$

$$= \underbrace{\left[\int_0^1 dx \right]}_{=1} \left[\int_0^1 (y-2) \, dy \right]$$

$$= \left[\frac{y^2}{2} - 2y \right]_0^1$$

$$= \left[\frac{(1)^2}{2} - 2(1) \right] - [0]$$

$$= \boxed{-\frac{3}{2}}$$

Note: When $S=R_{xy}$,
we end up with
Green's Thm.
Can you show this?

(Typed in review:)

When is \vec{F} Conservative in \mathbb{R}^3 ? Equivalent statements:In a connected region D (in which \vec{F} is cont.)...
"in one piece"

- Same as for \mathbb{R}^2 on 18.3.10, but
- ① \vec{F} is conservative
(i.e., $\vec{F} = \nabla f$ for some scalar potential func. f)
 - ② We have 1P: $\int_C \vec{F} \cdot d\vec{r}$
 - ③ $\int_C \vec{F} \cdot d\vec{r} = 0$ for every simple closed curve C in D

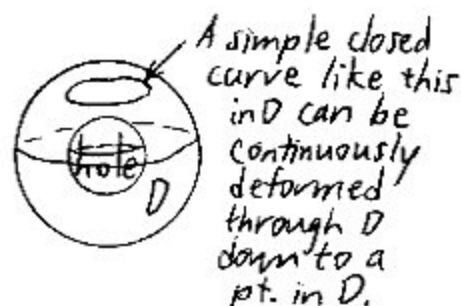
replace
 (4a) \rightarrow (4b) $\text{curl } \vec{F} = \vec{0}$ throughout D
 (i.e., \vec{F} is irrotational)
 if $\vec{F} = \langle M, N, P \rangle$ is "nice."

Note: $\int_C \vec{F} \cdot d\vec{r} = \int_C M dx + N dy + P dz$

If we start with (4b), then we require that D be simply connected,

different idea
from \mathbb{R}^2 case

See pp. 1017-8.
This is s.c.:



A donut (torus) is not.
There are simple closed curves in it that don't have capping surfaces.

Note (4b) is a very natural extension of (4a) into \mathbb{R}^3 !!

$$\begin{aligned}\overrightarrow{\text{curl}} \vec{F} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} \\ &= \left\langle \frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}, -\left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z}\right), \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right\rangle \\ &= \left\langle \frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}, \frac{\partial M}{\partial z} - \frac{\partial P}{\partial x}, \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right\rangle\end{aligned}$$

Observe:

$$\overrightarrow{\text{curl}} \vec{F} = \vec{0} \iff \frac{\partial P}{\partial y} = \frac{\partial N}{\partial z}, \frac{\partial M}{\partial z} = \frac{\partial P}{\partial x}, \text{ and } \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

from (4a)
for \mathbb{R}^2 !!

Also:

If $\vec{F}(x,y) = \langle M(x,y), N(x,y) \rangle$ is "nice" in \mathbb{R}^2 , we can go to the \mathbb{R}^3 case by writing:

$$\vec{F}(x,y) = \langle M(x,y), N(x,y), \overset{\text{zero}}{0} \rangle$$

$$\text{Then, } \overrightarrow{\text{curl}} \vec{F} = \langle 0, 0, \underbrace{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}_{\text{"scalar curl"}} \rangle$$

$$\text{This is } \vec{0} \iff \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

SECTIONS 18.6 AND 18.7: ADDITIONAL NOTES AND REVISIONS

SECTION 18.6: DIVERGENCE (GAUSS'S) THEOREM

Instead of doing my Example in my notes (#8), I will do the following Example:

Example

Find the flux of $\mathbf{F}(x, y, z) = \langle 2x, x^2 z^3, 5z \rangle$ through any sphere S of radius 4.

Solution

$$\text{Flux} = \iint_S \mathbf{F} \bullet \mathbf{n} \, dS = \iiint_Q (\text{div } \mathbf{F}) \, dV, \text{ where}$$

$$\begin{aligned} \text{div } \mathbf{F} &= \frac{\partial}{\partial x}(2x) + \frac{\partial}{\partial y}(x^2 z^3) + \frac{\partial}{\partial z}(5z) \\ &= 2 + 0 + 5 \\ &= 7 \end{aligned}$$

and Q is the region bounded by S .

$$\begin{aligned} \text{Flux} &= \iiint_Q 7 \, dV \\ &= 7 \iiint_Q dV \\ &= 7 (\text{Volume of } Q) \\ &= 7 \left(\frac{4}{3} \pi (4)^3 \right) \end{aligned}$$

since the volume of a sphere of radius r is $\frac{4}{3} \pi r^3$

$$\begin{aligned} &= 7 \left(\frac{256\pi}{3} \right) \\ &= \frac{1792\pi}{3} \end{aligned}$$

SECTION 18.7: STOKES'S THEOREM

I will skip my Example (#6).

I may show in class why Green's Theorem is merely a special case of Stokes's Theorem.

We will make the usual assumptions for Stokes's Theorem.
According to the theorem,

$$\text{Work } W = \oint_C \mathbf{F} \bullet \mathbf{T} \, ds = \iint_S (\mathbf{curl} \, \mathbf{F}) \bullet \mathbf{n} \, dS$$

If S is a region of the xy -plane, we can call it R , and we use $\mathbf{n} = \mathbf{k}$:

$$\text{Work } W = \oint_C \mathbf{F} \bullet \mathbf{T} \, ds = \iint_R (\mathbf{curl} \, \mathbf{F}) \bullet \mathbf{k} \, dA$$

This is called the vector form of Green's Theorem. Why?

$$\text{Let } \mathbf{F}(x, y, 0) = \langle M(x, y), N(x, y), 0 \rangle.$$

$$\text{You will find that } (\mathbf{curl} \, \mathbf{F}) \bullet \mathbf{k} = \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}.$$

We then have:

$$\begin{aligned} \text{Work } W &= \oint_C \mathbf{F} \bullet \mathbf{T} \, ds = \iint_R (\mathbf{curl} \, \mathbf{F}) \bullet \mathbf{k} \, dA \\ &= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \end{aligned}$$

The last expression should look familiar!

“COMING FULL CIRCLE” IN CALCULUS

The Generalized Stokes’s Theorem covers all of the major vector calculus theorems in this chapter, as well as the classic Fundamental Theorem of Calculus (FTC) from Calculus I.

What did the FTC say?

If f is integrable on the interval $[a, b]$ with antiderivative F on that interval,

$$\begin{aligned}\int_a^b f(x) \, dx &= \left[F(x) \right]_a^b \\ &= F(b) - F(a)\end{aligned}$$

The FTC relates an integral over an interval to information at the endpoints (the “boundary”) of that interval.

In Chapter 18, we related a higher-dimensional integral over a region to a lower-dimensional integral over the boundary of the region.

Calculus III is a very natural extension of Calculus I!!