

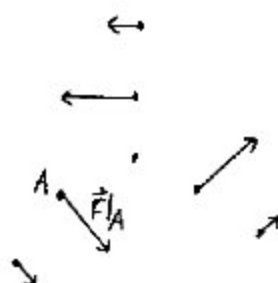


We'll study steady vector fields, in which vectors do not change with time.

Ex Velocity field for a kitchen sink (See 18.3.9, Note 2)

Show some of the vectors, enough to show a pattern.

Use  $A$  as the initial point for  $\vec{F}_A$ .



Sample units:  
 $\left\langle \frac{m}{sec}, \frac{m}{sec} \right\rangle$

Ex Electromagnetic force fields  
 Gravitational

Ex (Ch. 16) Gradient vector field

Ex  $f(x,y) = x^2 + y^2$  } Ch. 16 } Ch. 18  
 $\vec{F}(x,y) = \vec{\nabla} f(x,y) = \langle 2x, 2y \rangle$  (18.3)

We call  $f$  a potential function for  $\vec{F}$ .  
 $\left. \begin{array}{l} \text{lower} \\ \text{pot.} \end{array} \right\} \vec{F} = \vec{\nabla} f \left( \begin{array}{l} \text{Higher} \\ \text{pot.} \end{array} \right)$   
 $\left. \begin{array}{l} \text{lower} \\ \text{pot.} \end{array} \right\} \leftarrow -f \text{ in Physics so that:}$

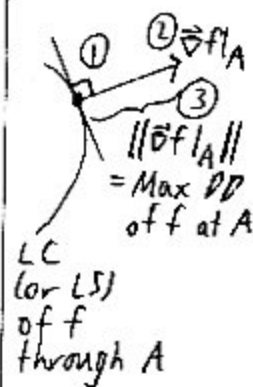
We call  $\vec{F}$  a conservative vector field, because  
 $\vec{F} = \vec{\nabla} f$  for some scalar func.  $f$   
 (i.e.,  $\vec{F}$  has a potential function).

Given a scalar  
 multivariable  
 func. in Ch. 16  
 what vector  
 field did we  
 construct?  
 VVF

Like the 6.9.9-  
 must be  
 conservative  
 to have potential.

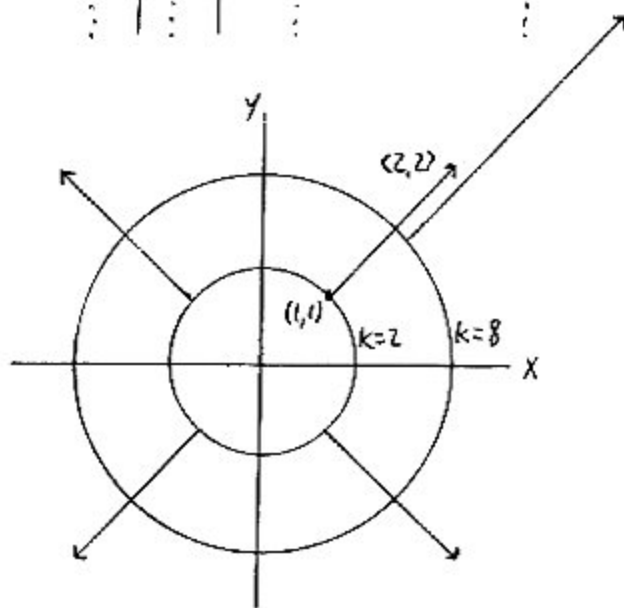
Recall (from 16.6):

- ①  $\underbrace{\nabla f|_A}_{= \vec{F}|_A \text{ here}} \perp$  level curve/surface <sup>LC</sup> / <sup>LS</sup> of the potential  $f$  containing  $A$
- ②  $\nabla f|_A$  points in direction of max rate of  $\nearrow$  of  $f$  at  $A$ .
- ③ Its length,  $\|\nabla f|_A\|$  is that max rate of  $\nearrow$ .



Table

A		$\vec{F}(x,y) =$ $\nabla f(x,y) =$ $\langle 2x, 2y \rangle$	(LC thru A) $k =$ $f(x,y) =$ $x^2 + y^2$
x	y	$\langle 2x, 2y \rangle$	$x^2 + y^2$
1	1	$\langle 2, 2 \rangle$	2
-1	1	$\langle -2, 2 \rangle$	2
2	2	$\langle 4, 4 \rangle$	8
$\vdots$	$\vdots$	$\vdots$	$\vdots$



$\vec{F}|_A$   
 $\nabla f|_A$

(B)  $\vec{\nabla}$  Operator  
del/nabla

$$\vec{\nabla} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \quad (\text{Informal})$$

$$\vec{\nabla} f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle \quad \text{gives a VVF (vector field)}$$

↑  
scalar  
func.

}  $\mathbb{R}^3$   
versions

How does  $\vec{\nabla}$  operate on VVFs?

(Assume  $\vec{F}$  is "nice": components are cont. and have cont. 1<sup>st</sup>-order PDs where we care.)

(C)  $\overrightarrow{\text{curl}} \vec{F} = \vec{\nabla} \times \vec{F}$  ( $\vec{F}$  in  $\mathbb{R}^3$ )

(If  $\vec{F} = \langle F_1, F_2 \rangle$  in  $\mathbb{R}^2$ ,  
write  $\langle F_1, F_2, 0 \rangle$ )

↑  
zero

gives a VVF (vector field)

Ex (#18) If  $\vec{F}(x, y, z) = \langle \underbrace{x^3 \ln z}_{M(x, y, z)}, \underbrace{x e^{-y}}_{N(x, y, z)}, \underbrace{-(y^2 + 2z)}_{P(x, y, z)} \rangle$ ,  
find  $\text{curl } \vec{F}$ .

$$\overrightarrow{\text{curl}} \vec{F} = \vec{\nabla} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^3 \ln z & x e^{-y} & -(y^2 + 2z) \end{vmatrix}$$

$$= \left\langle \frac{\partial}{\partial y} [-(y^2 + 2z)] - \frac{\partial}{\partial z} (x e^{-y}) \right\rangle$$

$$\ominus \left[ \frac{\partial}{\partial x} [-(y^2 + 2z)] - \frac{\partial}{\partial z} (x^3 \ln z) \right],$$

$$\frac{\partial}{\partial x} (x e^{-y}) - \frac{\partial}{\partial y} (x^3 \ln z) \right\rangle$$

$$= \langle -2y, x^3 \cdot \frac{1}{z}, e^{-y} \rangle$$

$$= \boxed{\langle -2y, \frac{x^3}{z}, e^{-y} \rangle}$$

Marsden uses  $C^1$  instead of "nice".  
"Smooth" implies derivs non-0, perhaps.

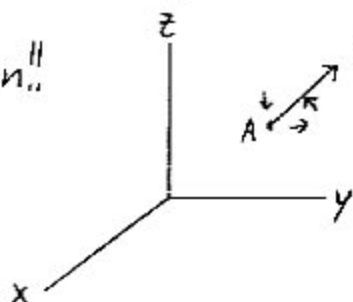
In 18.7, Suokowski says  
rot  $\vec{F} = (\overrightarrow{\text{curl}} \vec{F}) \cdot \vec{n}$

where  $\vec{F} =$   
velocity  $\nabla\phi$

① Interpreting  $[\vec{\text{curl}} \vec{F}]_A$  (in a coordinate-free sense) Don't need Cartesian!

Explained on pp. 1013-4 using Stokes' Thm. in 18.7.

"Local" rotation!!



vorticity vector

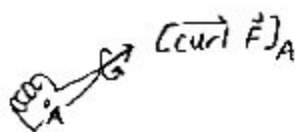
Note:  $\vec{F}_A$ , itself, is irrelevant!! (limit idea)

Direction of  $[\vec{\text{curl}} \vec{F}]_A$  indicates the axis of rotation of  $\vec{F}$  near  $A$ .

↙ which way does  $[\vec{\text{curl}} \vec{F}]_A$  point?

rotation is counter-clockwise if look from tip of curl vector towards the paddlewheel

Right-Hand Rule for curl

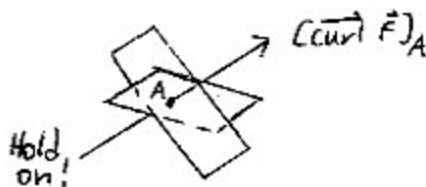


curling of fingers indicate "overall rotation" (see ↙) of  $\vec{F}$  near  $A$

Idea

Analogous to idea of  $\nabla\phi$  at  $A$  max'ed in direction of  $\vec{\nabla}\phi_A$

At  $A$ , rotate this paddlewheel until its paddles revolve the fastest



$\|[\vec{\text{curl}} \vec{F}]_A\|$  indicates the strength of the rotational effect about near  $A$ . It equals twice the angular speed of the paddles about this axis. Sample units:  $\frac{\text{radians}}{\text{sec}}$  ← Time unit used for  $\vec{F}$

$\vec{\text{curl}} \vec{F} = \vec{0}$  throughout  $D \Leftrightarrow \vec{F}$  is irrotational in  $D$

see Snook 1016, MIT Munkres Calc II - F9 see HW

$$\textcircled{E} \text{ div } \vec{F} = \vec{\nabla} \cdot \vec{F}$$

divergence gives a scalar function

Ex (#18) If  $\vec{F}(x, y, z) = \langle x^3 \ln z, xe^{-y}, -(y^2 + 2z) \rangle$ ,  
find  $\text{div } \vec{F}$ .

$$\text{div } \vec{F} = \vec{\nabla} \cdot \vec{F}$$

$$= \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle x^3 \ln z, xe^{-y}, -(y^2 + 2z) \rangle$$

$$= \frac{\partial}{\partial x} (x^3 \ln z) + \frac{\partial}{\partial y} (xe^{-y}) + \frac{\partial}{\partial z} [-(y^2 + 2z)]$$

$$= 3x^2 \ln z + xe^{-y}(-1) + (-2)$$

$$= \boxed{3x^2 \ln z - xe^{-y} - 2}$$

Explained  
using Div. Thm.  
in 18.6  
Stewart 1094  
5ed ET

Ex Interpreting  $[\text{div } \vec{F}]_A$  (again, in terms of local behavior near  $A$ )

tendency of fluid to diverge from pt.  $A$

If  $[\text{div } \vec{F}]_A < 0$ , then there is a sink at  $A$ .

Tendency  $\begin{matrix} \nearrow A \leftarrow \\ \longrightarrow A \longrightarrow \\ \searrow A \rightarrow \end{matrix}$

alphabetical  
order  $\approx -$  to  $+$

If  $[\text{div } \vec{F}]_A > 0$ , then there is a source at  $A$ .

$\begin{matrix} \leftarrow A \rightarrow \\ \rightarrow A \rightarrow \\ \rightarrow A \rightarrow \end{matrix}$

Ex cooling  
gas -  
compressible

If  $[\text{div } \vec{F}]_A = 0 \Rightarrow$  neither.  $\begin{matrix} \rightarrow A \rightarrow \\ \rightarrow A \rightarrow \end{matrix}$

If  $\text{div } \vec{F} = 0$  throughout  $D \Rightarrow \vec{F}$  is divergence free.

Exs incompressible fluids,  
solenoidal electromagnetic fields  
(EM)

See 18.6.1 for units.

incl. water,  
pretty much

⑥ When is a Vector Field,  $\vec{F}$ , Conservative?

(Assume  $\vec{F}$  is "nice.")

$$\Leftrightarrow \vec{F} = \vec{\nabla} f \text{ for some scalar func. } f$$

$$\Leftrightarrow \overrightarrow{\text{curl}} \vec{F} = \vec{0} \quad (\text{if } \vec{F} \text{ nice in } \mathbb{R}^3)$$

(You'll prove  $\Rightarrow$  in HW! #22 Converse ( $\Leftarrow$ ) proven later in 18.7 on Stokes's Thm.)

Marsden Sed  
p. 551;  
In  $\mathbb{R}^2$ ,  $\vec{F}$  can  
be conserv.  
even if undef.  
at a finite #  
of pts.  
(provided  $f$   
also undef.  
there).  
Exceptional  
pts. not  
allowed in  $\mathbb{R}^2$ .

Larson: This is related to conservation of energy,  
for a particle moving in a conservative force field,  
the sum of its kinetic energy  
due to motion  
and its potential energy  
due to position  
is constant.

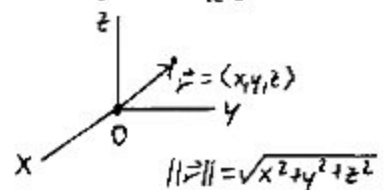
## (H) Inverse Square Fields are Conservative

Ex Gravity, Electric force (Coulomb's Law)



The magnitude of the force between these is inversely proportional to the square of the distance between them. Let one be at  $O$ .

2x distance  $\Rightarrow \frac{1}{4}$  of force  
3  $\frac{1}{9}$

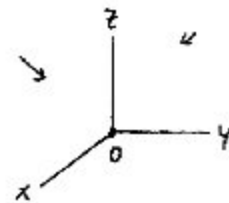
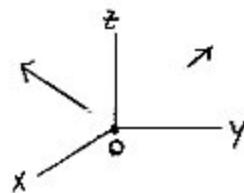


$$\vec{F}(x, y, z) = \underbrace{\left(\frac{c}{\|\vec{r}\|^2}\right)}_{\text{unit vector in direction of } \vec{r}} \vec{r} \text{ for some constant of proportionality, } c.$$

ensures that  $\|\vec{F}(x, y, z)\| = \frac{|c|}{\|\vec{r}\|^2}$

$$= \frac{c\vec{r}}{\|\vec{r}\|^3}, \text{ provided } \vec{r} \neq \vec{0}$$

If  $c > 0$ , repulsion (away from  $O$ )    If  $c < 0$ , attraction (towards  $O$ )



These vectors are  $\perp$  to spheres centered at  $O$ ,



level surfaces of potential

In  $\mathbb{R}^3$ , so OK that  $O$  is an exceptional pt.

Stewart sect. Ap. 1091, 3:

If  $\vec{F}$  comp's,  $f$  have cont. 2nd-order pds

$\vec{F}$  is conserv. :  $\vec{F} = \nabla f$ , where  $f(x, y, z) = -\frac{c}{\|\vec{r}\|}$  (✓ this!!)

### (I) Interesting IDs (in $\mathbb{R}^3$ )

$$\begin{aligned} \operatorname{div}(\operatorname{curl} \vec{F}) &= 0 \\ \operatorname{curl}(\nabla f) &= \vec{0} \quad (\text{see 18.1.3 figure}) \\ &\text{is conserv., remember?} \end{aligned}$$

$\operatorname{div}, \operatorname{curl}$  critical to Maxwell's Laws in EM!!



Marsden  
5ed, 290-2

## Ⓝ Flow Lines

(or Streamlines or Integral Curves)

If  $\vec{F}$  is a velocity field, then a particle placed in the field will trace out a flow line.

(See 15.2, 2)



Flow line carries "invisible" speed info.

If that's the path we want, how much does  $\vec{F}$  help us?

What if we want another path?

Even if there's a flow line from pt. A to pt. B, can we do better?

We'll discuss Work in 18.2 Ⓣ.