

REVIEW: 16.3-16.916.3: P.D.s1<sup>st</sup>-Order Ex

$$f_x(x, y) \text{ or } \frac{\partial f}{\partial x}(x, y)$$

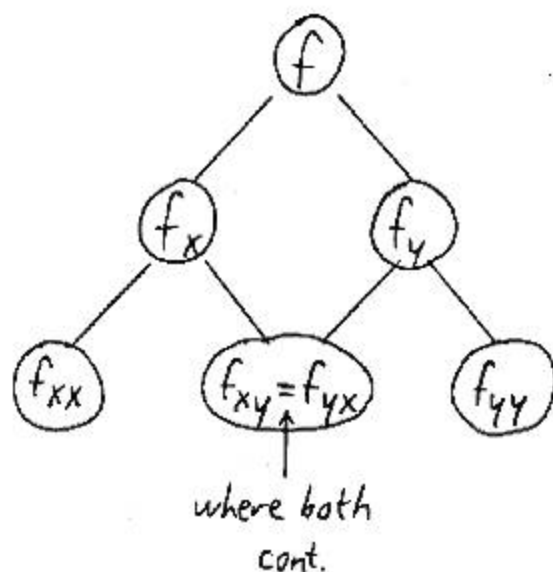
$$= \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h}$$

To find: Treat  $y$  as constant,  
Differentiate wrt  $x$ .

2<sup>nd</sup>-Order Exs

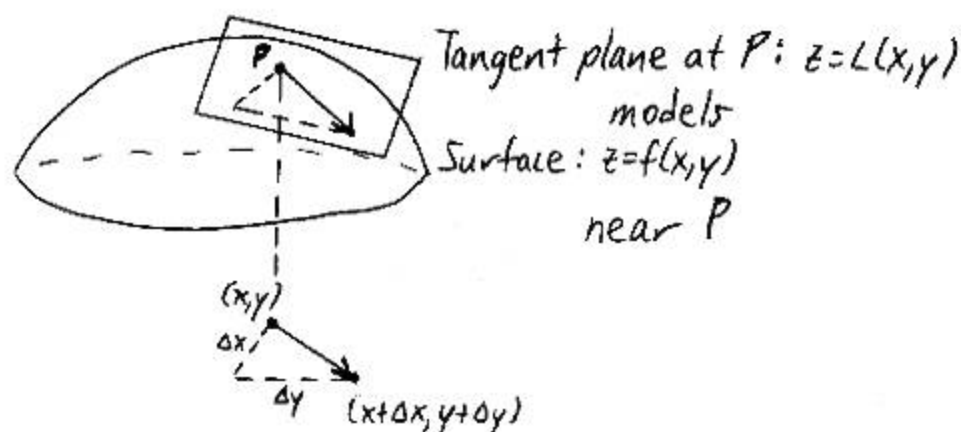
$$f_{xx} = (f_x)_x = \frac{\partial^2 f}{\partial x^2}$$

$$f_{xy} = (f_x)_y = \frac{\partial^2 f}{\partial y \partial x}$$



16.4: INCREMENTS and DIFFERENTIALS $\Delta x, \Delta y, \Delta z, \text{etc.}$  $dx, dy, dz, \text{etc.}$ 

Used to find linear approxs. for  $f$  near a seed point  $P(x, y, f(x, y))$ .



$$dx = \Delta x = \text{new } x - \text{old } x$$

$$dy = \Delta y = \text{new } y - \text{old } y$$

$dz =$  change in  $z$  along tangent plane

$$= (x \text{ slope})(x \text{ run}) + (y \text{ slope})(y \text{ run}) \quad \leftarrow \text{Idea: rise} = (\text{slope} \times \text{run})$$

$$= f_x(x, y) dx + f_y(x, y) dy$$

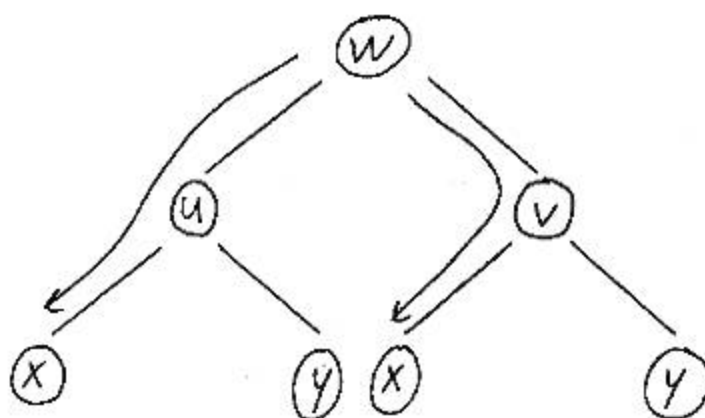
approximates  $\Delta z$ , the actual change in  $z$  along the surface

$$\text{We approx. } f(x + \Delta x, y + \Delta y) = f(x, y) + \Delta z$$

$$\text{by } L(x + \Delta x, y + \Delta y) = f(x, y) + dz.$$

Theory Notes

$f_x, f_y$  cont. on open region  $\Rightarrow f(x, y)$  diff'e there  
 $f$  diff'e at  $(a, b) \Rightarrow f$  cont. there

16.5: CHAIN RULESExAt end, write in terms of  $x, y$ 

$$\frac{\partial w}{\partial x} = \underbrace{\frac{\partial w}{\partial u} \frac{\partial u}{\partial x}}_{\text{Product along path } w \rightarrow x} + \underbrace{\frac{\partial w}{\partial v} \frac{\partial v}{\partial x}}_{\text{Product along path } w \rightarrow v \rightarrow x}$$

Product along  
path  $w \rightarrow x$ 

Add these path products.

If  $F(x, y) = 0$  describes a diff' e func.  $f$  such that  $y = f(x)$ ,

$$\frac{dy}{dx} = -\frac{F_x}{F_y} \quad (\text{"Negative reciprocal"})$$

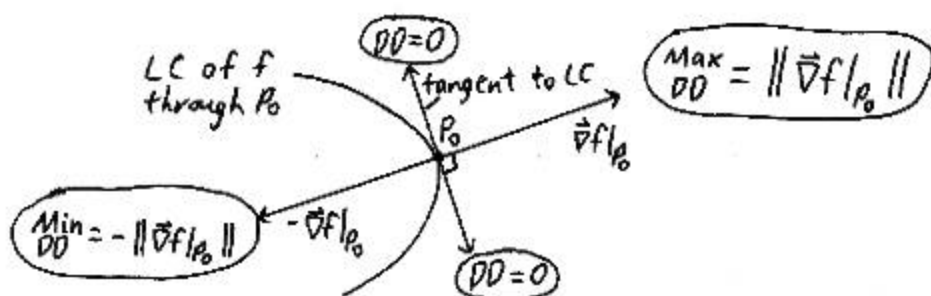
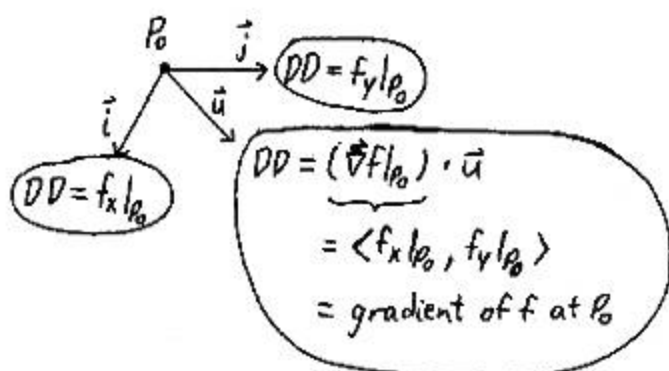
$$\begin{array}{c} F \\ / \quad \backslash \\ x \quad y \end{array} \leftarrow \text{treat as indep.}$$
If  $F(x, y, z) = 0$ '  $z = f(x, y)$ ,

$$\frac{\partial z}{\partial x} = -\frac{F_x}{F_z}, \quad \frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$$

$$\begin{array}{c} F \\ / \quad \backslash \\ x \quad y \quad z \end{array} \leftarrow \text{treat as indep.}$$

16.6: DDs / 16.7

$f(x,y)$

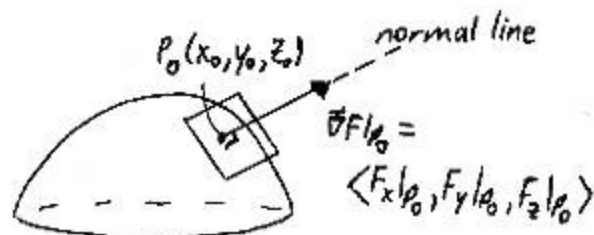


$f(x,y,z)$

(LCs) → (LSs)  
 Level curves → Level surfaces  
 Tangent line → Tangent plane

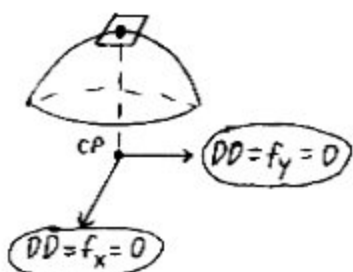
$$Eq.: (F_x|_{P_0})(x-x_0) + (F_y|_{P_0})(y-y_0) + (F_z|_{P_0})(z-z_0) = 0$$

Ideas analogous to  $f(x,y)$   
 Ex  $\nabla f \perp$  (Tangent to LC/LS)



16.8: OPTIMIZATION I

CPs are the only places where L. Max./Min. can occur.



$(a, b)$  is a CP  $\Leftrightarrow$   
 ①  $(a, b)$  in  $\text{Dom}(f)$   
 ①  $\vec{\nabla}f(a, b) = \langle f_x(a, b), f_y(a, b) \rangle = \vec{0}$   
 or ② DNE

2<sup>nd</sup> Derivative Test to Classify CPs

$$D = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} \left. \vphantom{\begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix}} \right\} \begin{array}{l} \text{Assume all} \\ \text{cont.} \end{array}$$

$$= f_{xx}f_{yy} - (f_{xy})^2$$

At a CP where  $\vec{\nabla}f = \vec{0}$ ,


① If  $D > 0$ ,

①a If  $f_{xx}$  (or  $f_{yy}$ )  $< 0$   $\text{☹} \Rightarrow$  L. Max.  
 ①b  $>$   $\text{☺} \Rightarrow$  L. Min.

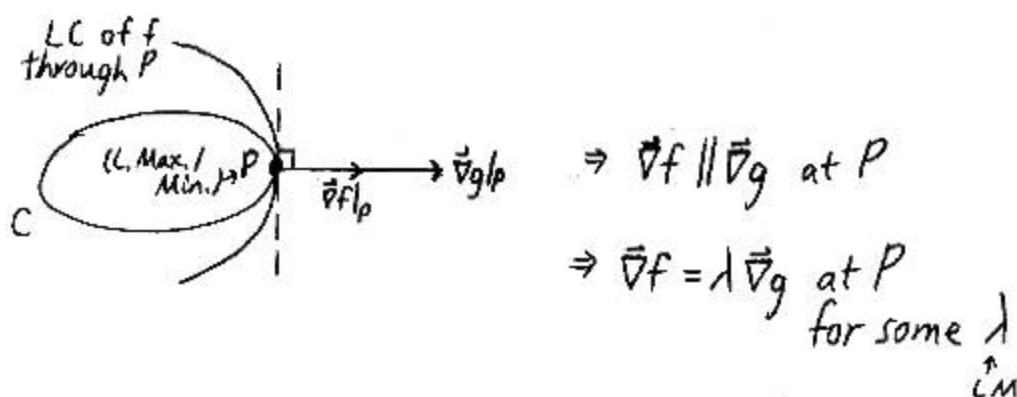
② If  $D < 0 \Rightarrow$  Saddle Pt.

③ If  $D = 0 \Rightarrow$  No info

## 16.9: CONSTRAINED OPTIMIZATION - LAGRANGE MULTIPLIERS (LMs)

Ex  $f$   ← Find L. or A. Max./Min. [Pts.] of  $f$  along [the image of]  $C$ .

$$C: g(x,y) = 0$$



$$\text{Solve } \begin{cases} \vec{\nabla} f(x,y) = \lambda \vec{\nabla} g(x,y) \\ g(x,y) = 0 \end{cases} \text{ for } (x,y,\lambda)$$

$\uparrow$   
can differ among  $(x,y)$  candidates  
don't have to find

Evaluate  $f$  at the candidates, and compare.

See Strategies for Classifying, Solving Systems.