

6.2: KERNEL + RANGE

Let  $T: V \rightarrow W$  be a L.T.

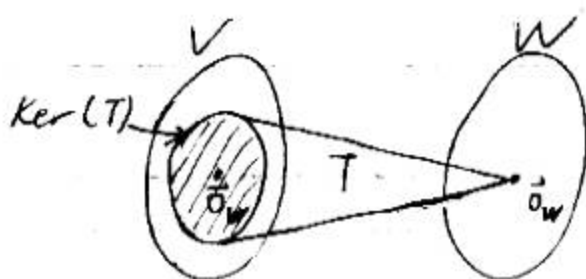
(A) Ker(T)

= kernel of  $T$

$$= \{ \vec{v} \text{ in } V \mid T(\vec{v}) = \vec{0}_W \}$$

= set of vectors in  $V$  that  $T$  maps to  $\vec{0}$  in  $W$ .

is a subspace of  $V$  (pp. 339-40)



what vector  
in  $V$  must be  
in the kernel?

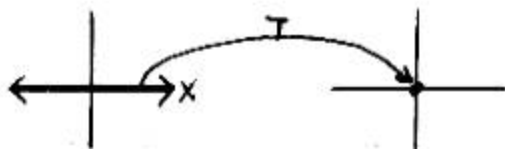
subspace

Ex  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , find  $\text{Ker}(T)$  if  
 $T(x, y) = \underline{(0, y)}$  ← projection on  $y$ -axis  
 what makes  
 this =  $\vec{0}$ ?

$$\begin{cases} \cancel{0=0} \\ y=0 \end{cases}$$

$$\begin{cases} x=t \text{ (free)} \\ y=0 \end{cases}$$

$$\text{Ker}(T) = \{(t, 0) \mid t \text{ is a real } \#\} \\ = \text{x-axis}$$



$T(\vec{x}) = A\vec{x}$  defines  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  (A LT can be given by a matrix.)

$$\text{Ker}(T) = \{\vec{x} \text{ in } \mathbb{R}^n \mid A\vec{x} = \vec{0}\} \\ = N(A), \text{ the nullspace of } A$$

Its dimension = nullity(T)  
or nullity(A)

Your book  
stiles w/x

$$\text{Ex } T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$T(\vec{x}) = A\vec{x}, \vec{x} \text{ in } \mathbb{R}^3$$

$$A = \begin{bmatrix} 2 & 4 & 6 \\ 0 & 1 & 3 \end{bmatrix}$$

Find a basis for  $\text{Ker}(T)$  as a subspace of  $\mathbb{R}^3$ .

Solution

Solve  $A\vec{x} = \vec{0}$  and find a basis for  $N(A)$ .

$$\left[ \begin{array}{ccc|c} 2 & 4 & 6 & 0 \\ 0 & 1 & 3 & 0 \end{array} \right]$$

$$\stackrel{\text{RRE}}{\sim} \left[ \begin{array}{ccc|c} 1 & 0 & -3 & 0 \\ 0 & 1 & 3 & 0 \end{array} \right]$$

$$\begin{cases} x_1 - 3x_3 = 0 \\ x_2 + 3x_3 = 0 \end{cases}$$

$$\begin{cases} x_1 = 3x_3 \\ x_2 = -3x_3 \end{cases}$$

$$x_3 = t$$

$$\begin{cases} x_1 = 3t \\ x_2 = -3t \\ x_3 = t \end{cases}$$

$$\vec{x} = t \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix}, t \text{ is any real \#} \left. \vphantom{\begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix}} \right\} \begin{array}{l} \text{Ker}(T): \\ \text{line in } \mathbb{R}^3 \end{array}$$

$$\text{Basis: } \left\{ \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix} \right\}$$

$$\text{nullity}(T) = 1$$

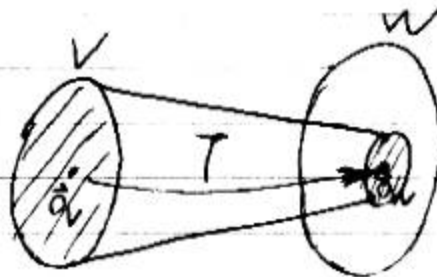
up to 6

Read Exs 1-6

### ③ Range(T)

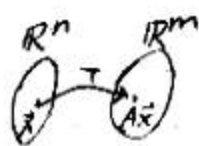
$$= \{T(\vec{v}) \mid \vec{v} \text{ is in } V\} \text{ (images)}$$

is a subspace of  $W$



$$T(\vec{x}) = A\vec{x}$$

m x n



Then,  $\text{Range}(T) = \{A\vec{x} \mid \vec{x} \text{ is in } \mathbb{R}^n\}$

$$= \{\vec{b} \text{ in } \mathbb{R}^m \mid A\vec{x} = \vec{b} \text{ is consistent}\}$$

$$= \text{Col}(A), \text{ the column space of } A$$

Its dimension = rank(T) or rank(A)

Ex  $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$   
 $T(\vec{x}) = A\vec{x}, \vec{x} \text{ in } \mathbb{R}^4$

$$A = \begin{bmatrix} 1 & 2 & 4 & 3 \\ 1 & 2 & 5 & 5 \\ 2 & 4 & 8 & 6 \end{bmatrix}$$

Find a basis for  $\text{Range}(T)$  as a subspace of  $\mathbb{R}^3$ .

Solution

→ row-echelon "shape"

$$A \sim \begin{bmatrix} 1 & 2 & 4 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

↑      ↑  
 Cols 1, 3 are pivot cols.

Take cols. 1, 3 from  $A$ .

$$\text{Basis} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 8 \end{bmatrix} \right\}$$

$\vec{v}_1$                        $\vec{v}_2$

Up to 11

Also,  $\text{Range}(T) = \text{Span}(\{\vec{v}_1, \vec{v}_2\}) = \text{"plane in } \mathbb{R}^3\text{"}$   
 $\text{rank}(T) = 2$

### © Sum Formulas

$$\textcircled{4.6F} \text{rank}(T) + \text{nullity}(T) = n$$

$\updownarrow$                        $\updownarrow$                        $\updownarrow$   
 $\dim(\text{Range}(T)) + \dim(\text{Ker}(T)) = \dim(\text{domain}, V)$

$$\underline{T(\vec{x}) = A\vec{x}}$$

$$[A] \sim \begin{bmatrix} \text{row-ech} \\ \text{shape} \end{bmatrix}$$

$n = \# \text{ cols}$

$\text{rank}(T) = \# \text{ pivot cols}$   
 $\text{nullity}(T) = \# \text{ nonpivot cols}$

Read Exs 8, 9

Ex  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$   
 $T(\vec{x}) = A\vec{x}$

from  
 $\text{Ker}(T)$

$$A \sim \begin{bmatrix} 2 & 4 & 6 \\ 0 & 1 & 3 \end{bmatrix}$$


$$\left( \sim \begin{bmatrix} 1 & 8 & -3 \\ 0 & 1 & 3 \end{bmatrix} \right)$$

Be aware of  
 variations of  
 same?

$$\begin{aligned} \text{rank}(T) &= \dim(\text{Range}(T)) = 2 \\ \text{nullity}(T) &= \dim(\text{Ker}(T)) = n - \text{rank}(T) \\ &= 3 - 2 \\ &= 1 \end{aligned}$$

Up to 35

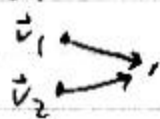
① When is  $T$  "One-to-One" (1-1)?

$\Leftrightarrow$  For each  $\vec{w}$  in  $\text{Range}(T)$   
 its preimage = {vector} 

$\Leftrightarrow$  whenever  $T(\vec{v}_1) = T(\vec{v}_2)$ , then  $\vec{v}_1 = \vec{v}_2$



NO:



can't have 2  
 vectors w/  
 same image

$A$  LT is 1-1  $\Leftrightarrow \text{Ker}(T) = \{\vec{0}\}$  proof (optional) p. 344

p. 344  
not in book!

$$T(\vec{x}) = A\vec{x} \quad \text{m} \times \text{n}$$

Read Ex 10

only  $\vec{0}_V \rightarrow \vec{0}_W$

$$\mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\begin{pmatrix} \vec{x} \end{pmatrix} \rightarrow \begin{pmatrix} A\vec{x} \end{pmatrix}$$

"T is 1-1" means " $A\vec{x} = \vec{b}$  has 0 or 1 sol'n for every  $\vec{b}$  in  $\mathbb{R}^m$ " 0 sol'n Range(T)

" $\text{Ker}(T) = \{\vec{0}\}$ " means " $A\vec{x} = \vec{0}$  has only the  $\vec{0}$  sol'n" only  $\vec{0}_{\mathbb{R}^n} \rightarrow \vec{0}_{\mathbb{R}^m}$

Each col. of a row-ech. shape of  $A$  has a **PP**

Ex [A] row ech. shape

$$\begin{bmatrix} \textcircled{1} & 0 \\ 0 & \textcircled{1} \\ 0 & 0 \end{bmatrix}$$

$$[A|\vec{0}] \sim \begin{bmatrix} 1 & 0 & | & 0 \\ 0 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = 0 \\ x_2 = 0 \end{matrix}$$

$$\left. \begin{matrix} T: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \\ T(\vec{x}) = A\vec{x} \end{matrix} \right\} \text{ is 1-1 (rank=2)}$$

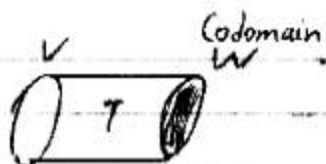
$A$  LT is 1-1  $\Leftrightarrow \text{rank}(T) = n$   
(#pivot cols. = #cols.)

Why?

$$\text{rank}(T) + \underbrace{\text{nullity}(T)}_{\dim(\text{Ker}(LT))} = n$$

$$= 0 \Leftrightarrow T \text{ is 1-1}$$

⑤ When is  $T$  "Onto"?



$\leftrightarrow$  each  $\vec{w}$  in  $W$  has a nonempty preimage  $\rightarrow \vec{v}$

$\leftrightarrow \text{Range}(T) = W$

$\leftrightarrow \text{rank}(T) = \text{dim}(W)$   
= dim of Range

Range  
= Codomain

If  $T(\vec{x}) = A\vec{x}$

$T$  is onto  $\Leftrightarrow A\vec{x} = \vec{b}$  is consistent for every  $\vec{b}$  in  $\mathbb{R}^m$

$\Leftrightarrow A$ 's cols. span  $\mathbb{R}^m$

$\Leftrightarrow$  Each row of a row-ech.  $\vec{x}$ 's  $\mathbb{R}^n \rightarrow \mathbb{R}^m$  all  $\vec{b}$ 's are hit  
 shape of  $A$  has a (PP)

not in book

is what?

Ex  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$   $\text{dim}(W)$   
 $T(\vec{x}) = A\vec{x}$

$[A]$  row-ech. shape  $\begin{bmatrix} 2 & 1 & 4 \\ 0 & 3 & 5 \end{bmatrix}$  each row has a (PP)

$T$  is (onto)

⑥ What if  $\text{dim}(V) = \text{dim}(W)$ ?

$\Rightarrow$  A linear  $T: V \rightarrow W$

① is one-to-one  $\swarrow$  either both  
 ② is onto  $\searrow$  or neither  
 ( $\approx$  basis)

$$\text{Ex } T: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \\ T(\vec{x}) = A\vec{x}$$

$$[A] \sim \begin{bmatrix} 2 & -2 & 1 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

We have a full "set" of PPs.  
(down the main diagonal)  
so  $T$  is 1-1 and onto.  $T$  is an isomorphism.

Read Ex 11

## ⑥ Isomorphisms of Vector Spaces

$V$  and  $W$  are isomorphic if there is a one-to-one and onto linear  $T: V \rightarrow W$  that "marries" the vectors of  $V$  with the vectors of  $W$ .



$$\Leftrightarrow \dim(V) = \dim(W) \quad (\text{if } \infty)$$

Ex  $\mathbb{R}^3 \cong M_{3,1} \cong M_{1,3} \cong P_2 \cong$  a 3-D subspace of  $\mathbb{R}^4$

"Natural" correspondences

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \leftrightarrow \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \leftrightarrow [c_1 \ c_2 \ c_3] \leftrightarrow c_1 + c_2x + c_3x^2 \leftrightarrow \begin{cases} \text{Basis: } \{\vec{b}_1, \vec{b}_2, \vec{b}_3\} \\ T: \text{This space} \rightarrow \mathbb{R}^3 \\ T(c_1\vec{b}_1 + c_2\vec{b}_2 + c_3\vec{b}_3) = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \end{cases}$$

a vector in the space  $\uparrow$  coord in  $\mathbb{R}^3$

These spaces "act the same" wrt (with respect to) "vector +", "scalar mult."

Read Ex 12

webster  
ISO = equal, homog,  
uniform  
morph = form  
Gr = intellectuals  
Eman = engineer,  
lawyer

no bijection

Me:  
You can't have  
 $\infty$ -dim V's that  
are isom, but  
that story's more  
complicated

a basis in your  
lur lil hands  
could be 06,0V

or  $c_3 + c_2x + c_1x^2$

Adding vectors  
in  $\mathbb{R}^3$  is  
equiv. to  
adding polys.  
in  $P_2$ .