

Nonstandard Bases

Review Ex $T: V \rightarrow W$
 $(\mathbb{R}^2) \quad (\mathbb{R}^2)$

$$T(x_1, x_2) = (x_1 - x_2, 3x_1) = \begin{bmatrix} 1 & -1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

B : ordered basis for V

$$B = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$\vec{v}_1 \quad \vec{v}_2$ (standard for now)

B' : W

Usually standard basis for W

$$B' = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$\vec{w}_1 \quad \vec{w}_2$

$$A = \left[[T(\vec{v}_1)]_{B'}, [T(\vec{v}_2)]_{B'} \right] = \begin{bmatrix} 1 & -1 \\ 3 & 0 \end{bmatrix}$$

If $\vec{v} = (5, 3)$, say \Rightarrow

$$\underset{\substack{\uparrow \\ \text{applies } T}}{A} \vec{v} = \begin{bmatrix} 1 & -1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 15 \end{bmatrix}$$

$$\checkmark: T(\vec{v}) = (5-3, 3(5)) = (2, 15) \text{ or } \begin{bmatrix} 2 \\ 15 \end{bmatrix}$$

Now

$$\text{Say } B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$$

$\vec{v}_1 \quad \vec{v}_2$

Now, $A =$ matrix for T relative to B and B'

$$= \left[\begin{array}{cc} [T(\vec{v}_1)]_{B'} & [T(\vec{v}_2)]_{B'} \end{array} \right]$$

where:

if nonstandard,
solve system

$$T(\vec{v}_1) = T(1, 1) = (0, 3) = 0\vec{w}_1 + 3\vec{w}_2$$

$$\Rightarrow [T(\vec{v}_1)]_{B'} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}_{B'}$$

$$T(\vec{v}_2) = T(2, 1) = (1, 6) = 1\vec{w}_1 + 6\vec{w}_2$$

$$\Rightarrow [T(\vec{v}_2)]_{B'} = \begin{bmatrix} 1 \\ 6 \end{bmatrix}_{B'}$$

$$= \begin{bmatrix} 0 & 1 \\ 3 & 6 \end{bmatrix}$$

Then, $[T(\vec{v})]_{B'} = A [\vec{v}]_B$

↑
applies T to "weird coordinates" of \vec{v}
relative to the "weird basis" B

result: the "ordinary coordinates" of $T(\vec{v})$
relative to the "ordinary basis" B'

Ex $B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$
 $\vec{v}_1 \quad \vec{v}_2$

$\vec{v} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$ or $(5, 3)$

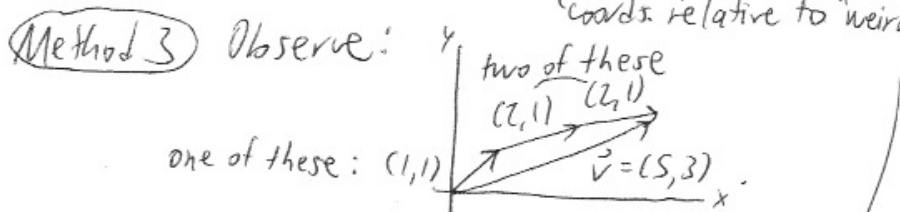
Method 1 Observe: $\vec{v} = \begin{bmatrix} 5 \\ 3 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

Method 2 Solve: $\vec{v} = \begin{bmatrix} 5 \\ 3 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

i.e., $\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$

$\Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

↑ coords. relative to "weird basis" B



In any case $\Rightarrow [\vec{v}]_B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$[T(\vec{v})]_{B'} = A [\vec{v}]_B = \begin{bmatrix} 0 & 1 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 15 \end{bmatrix}$, as in Review Ex
 (standard)

$\checkmark: T(5, 3) = (2, 15)$ or $\begin{bmatrix} 2 \\ 15 \end{bmatrix}$

