

CH. 7: EIGENVALUES and EIGENVECTORS7.1: INTROⒶ Definitions

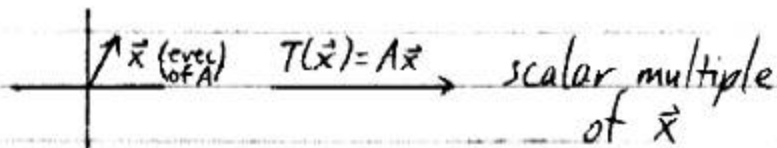
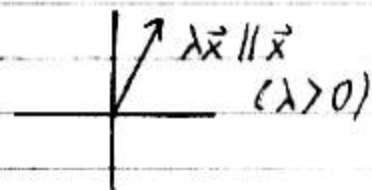
$$A - n \times n$$

The scalar λ ("lambda") is an eigenvalue^(eval) of $A \iff$ there exists $\vec{x} \neq \vec{0}$ such that $A\vec{x} = \lambda\vec{x}$.

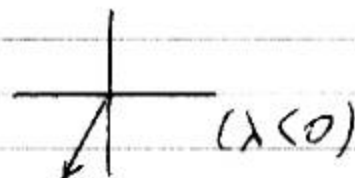
\vec{x} is then an eigenvector^(evec) of A corresp. to λ .

Idea

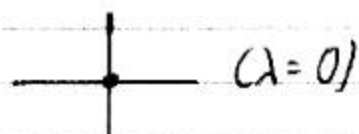
if we apply

shrinks if
 $\lambda = \frac{1}{2}$ 

or



or



⑧ Verifying Evals, Evecs

6.1.4-206

Ex Verify that $\lambda = 3$ is an eval
of $A = \begin{bmatrix} 5 & -3 \\ -4 & 9 \end{bmatrix}$ and that
 $\vec{x} = (3, 2)$ is a corresp. evec.

Solution

$$A\vec{x} = \begin{bmatrix} 5 & -3 \\ -4 & 9 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 9 \\ 6 \end{bmatrix}$$

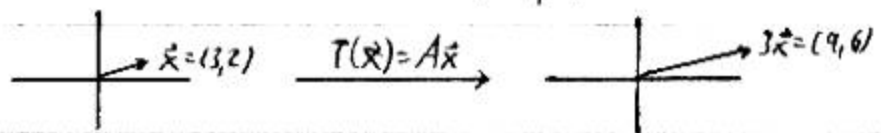
$$\lambda\vec{x} = 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 9 \\ 6 \end{bmatrix}$$

same

So, $A\vec{x} = \lambda\vec{x}$ where $\lambda = 3, \vec{x} = (3, 2)$. ✓
eval-evec pair

3 is a stretching factor.



6.1.6-20F

Ex Is $\vec{x} = (1, -2, 1)$ an evec. of

$A = \begin{bmatrix} 3 & 6 & 7 \\ 3 & 3 & 7 \\ 5 & 6 & 5 \end{bmatrix}$? If so, find its
corresp. eval.

$$A\vec{x} = \begin{bmatrix} 3 & 6 & 7 \\ 3 & 3 & 7 \\ 5 & 6 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -2 \\ 4 \\ -2 \end{bmatrix}$$

(Is this a scalar multiple
of $\vec{x} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$? YES)

$$= (-2\vec{x} \text{ or}) -2 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

\vec{x} is an evec
its corresp. eval
is -2

eval-evec pair

① Eigenspaces

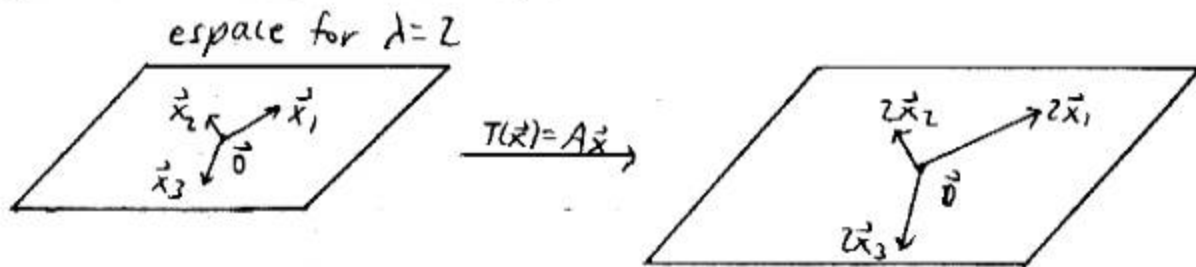
If A ($n \times n$) has an eval λ , then

$$E_\lambda = \underbrace{\{\text{all evecs of } \lambda\} \cup \{\vec{0}\}}_{\text{throw in } \vec{0}}$$

is the eigenspace ^(Espace) of λ .
a subspace of \mathbb{R}^n

Ex

What happens
to \vec{x}_i under
this transf?



Proof: E_λ is a subspace of \mathbb{R}^n

$$E_\lambda \neq \emptyset, E_\lambda \subseteq \mathbb{R}^n$$

Let \vec{x}_1, \vec{x}_2 be in E_λ . (They're evecs of λ or $\vec{0}$.) $A\vec{x}_1 = \lambda\vec{x}_1$, $A\vec{x}_2 = \lambda\vec{x}_2$

Show $\vec{x}_1 + \vec{x}_2$ is in E_λ : (i.e., $A(\vec{x}_1 + \vec{x}_2) = \lambda(\vec{x}_1 + \vec{x}_2)$)

$$A(\vec{x}_1 + \vec{x}_2) = A\vec{x}_1 + A\vec{x}_2 = \lambda\vec{x}_1 + \lambda\vec{x}_2 = \lambda(\vec{x}_1 + \vec{x}_2)$$

Show $c\vec{x}_1$ is in E_λ : (c is any scalar) (i.e., $A(c\vec{x}_1) = \lambda(c\vec{x}_1)$)

$$A(c\vec{x}_1) = c(A\vec{x}_1) = c(\lambda\vec{x}_1) = \lambda(c\vec{x}_1)$$

$A\vec{x}_1 = \lambda\vec{x}_1$, even
if $\vec{x}_1 = \vec{0}$

① Finding Evals, Evecs

$$A - n \times n$$

When does $A\vec{x} = \lambda\vec{x}$ have nontrivial sol'ns \vec{x} (evecs)?

$$\begin{aligned} & A\vec{x} = \lambda\vec{x} \\ \Leftrightarrow & A\vec{x} = \lambda(I\vec{x}) \quad \text{More precisely, } I = I_n. \\ \Leftrightarrow & \vec{0} = \lambda I\vec{x} - A\vec{x} \quad \text{or: } A\vec{x} - \lambda I\vec{x} = \vec{0} \\ \Leftrightarrow & \vec{0} = (\lambda I - A)\vec{x} \quad (A - \lambda I)\vec{x} = \vec{0} \end{aligned}$$

When does $\underbrace{(\lambda I - A)}_{n \times n} \vec{x} = \vec{0}$ have nontrivial sol'ns \vec{x} ?

When $\det(\lambda I - A) = 0$ (Some books: $\det(A - \lambda I) = 0$)
 i.e., singular/noninvertible

How do we find evals?

$$\text{Solve } \det(\lambda I - A) = 0 \text{ for } \lambda.$$

characteristic polynomial of A

characteristic equation of A

Meyer 549:
 If A real skew-sym
 $(A^T = -A) \Rightarrow$
 A has pure imag. evals

Maybe no real evals!
 Ex $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ $\begin{matrix} \swarrow (x,y) \\ \searrow (y,-x) \end{matrix}$ $A \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ -x \end{bmatrix}$ No evecs. for real evals.
 $\det(\lambda I - A) = |\lambda I - A| = \begin{vmatrix} \lambda & -1 \\ 1 & \lambda \end{vmatrix} = \lambda^2 + 1$ has no real zeros/roots. No real evals!

How do we find the evecs corresp. to λ ?

We take the nonzero sol'ns of

$$(\lambda I - A) \vec{x} = \vec{0}$$

↑

Ex Find the evals and corresp. evecs of $A = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix}$.

Find evals Do not apply EROs now! EROs do not necessarily preserve evals.

Solve $|\lambda I - A| = 0$

$$\left| \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} - \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \right| = 0$$

$$\begin{vmatrix} \lambda - 1 & -2 \\ -3 & \lambda - 2 \end{vmatrix} = 0$$

$$\begin{aligned} (\lambda - 1)(\lambda - 2) - 6 &= 0 \\ \lambda^2 - 3\lambda + 2 - 6 &= 0 \\ \lambda^2 - 3\lambda - 4 &= 0 \end{aligned}$$

char. poly.
of A

char. eq.
of A

Here, in principle,
you can apply
EROs - we're
talking about
dets.

Sometimes (n odd?)
leading coeff.
is +1, not -1
if so $|\lambda I - A|$
vs. $|A - \lambda I|$

$$(\lambda - 4)(\lambda + 1) = 0$$

$$\lambda_1 = 4, \lambda_2 = -1$$

or QF (Quadratic Formula)

Find the evecs for $\lambda_1 = 4$

Find the nonzero sol's of

$$(\lambda I - A)\vec{x} = \vec{0}$$

$$[4I - A \mid \vec{0}]$$

$$\begin{bmatrix} 4-1 & 0-2 & \mid & 0 \\ 0-3 & 4-2 & \mid & 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -2 & \mid & 0 \\ -3 & 2 & \mid & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & -2 & \mid & 0 \\ 0 & 0 & \mid & 0 \end{bmatrix} \leftarrow \text{You better have a row of "0"s!"}$$

$$\text{RRE} \sim \begin{bmatrix} 1 & -\frac{2}{3} & \mid & 0 \\ 0 & 0 & \mid & 0 \end{bmatrix}$$

$$\begin{cases} x_1 - \frac{2}{3}x_2 = 0 \\ 0 = 0 \end{cases}$$

$$\begin{cases} x_1 = \frac{2}{3}x_2 \end{cases}$$

$$\text{Let } x_2 = t$$

write $4I$!

You better have a row of 0s!

[square $\vec{0}$]

7.1.8

$$\begin{cases} x_1 = \frac{2}{3}t \\ x_2 = t \end{cases}$$

$$\vec{x} = t \begin{bmatrix} \frac{2}{3} \\ 1 \end{bmatrix}, t \neq 0$$

($\vec{0}$ isn't an evec)

Shortcut when 1 free var:
 $\frac{2}{3} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} -\frac{2}{3} \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 sol'n \leftrightarrow cols from RRE form
 as weights, we get RHS

Find the evecs for $\lambda_2 = -1$

$$[(-1)I - A \mid \vec{0}]$$

$$\begin{bmatrix} -1-1 & 0-2 & \mid & 0 \\ 0-3 & -1-2 & \mid & 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & -2 & \mid & 0 \\ -3 & -3 & \mid & 0 \end{bmatrix}$$

$$\stackrel{\text{RRE}}{\sim} \begin{bmatrix} 1 & 1 & \mid & 0 \\ 0 & 0 & \mid & 0 \end{bmatrix}$$

$$x_1 + x_2 = 0$$

$$\Rightarrow x_1 = -x_2$$

Let $x_2 = t$

$$\begin{cases} x_1 = -t \\ x_2 = t \end{cases}$$

$$\vec{x} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}, t \neq 0$$

Shortcut:
 $(-1)[6] + (1)[6] = [0]$

In general, the char. poly. is n^{th} -degree in λ .
 A can have at most n real distinct evals.

If $n \geq 3$, I will give you the evals, unless...
 see my handout

(E) Triangular Matrices

Their evals are the
 main diagonal entries.

Ex $A = \begin{bmatrix} \textcircled{1} & 0 & 0 \\ 4 & \textcircled{-2} & 0 \\ 5 & 9 & \textcircled{0} \end{bmatrix}$

is lower triangular.

Evals: 1, -2, 0

Why?

$$A = \begin{bmatrix} d_1 & & 0 \\ \dots & d_2 & \\ \dots & \dots & d_n \end{bmatrix}$$

$$|\lambda I - A| = \begin{vmatrix} \lambda - d_1 & & 0 \\ \dots & \lambda - d_2 & \\ \dots & \dots & \lambda - d_n \end{vmatrix}$$

$$= (\lambda - d_1)(\lambda - d_2) \cdots (\lambda - d_n) \stackrel{\text{set}}{=} 0$$

$$\lambda = d_1, \lambda = d_2, \dots, \lambda = d_n$$

Similarly for \square

(F) More Exs.

8.1.20

Ex $\lambda = 7$ is one of the evals of

$$A = \begin{bmatrix} 7 & -4 & 4 \\ -4 & 5 & 0 \\ 4 & 0 & 9 \end{bmatrix}$$

Find the evecs corresp. to $\lambda = 7$.

$$\left[\begin{array}{ccc|c} \lambda I - A & 0 \\ \hline \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 7-7 & 0-(-4) & 0-4 & 0 \\ 0-(-4) & 7-5 & 0-0 & 0 \\ 0-4 & 0-0 & 7-9 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 0 & 4 & -4 & 0 \\ 4 & 2 & 0 & 0 \\ -4 & 0 & -2 & 0 \end{array} \right]$$

$$\text{RRE} \left[\begin{array}{ccc|c} 1 & 0 & \frac{1}{2} & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

\uparrow
 x_3 free

$$\begin{cases} x_1 + \frac{1}{2}x_3 = 0 \\ x_2 - x_3 = 0 \end{cases}$$

$$\begin{cases} x_1 = -\frac{1}{2}x_3 \\ x_2 = x_3 \end{cases}$$

Let $x_3 = t$

$$\begin{cases} x_1 = -\frac{1}{2}t \\ x_2 = t \\ x_3 = t \end{cases}$$

$$\vec{x} = t \begin{bmatrix} -\frac{1}{2} \\ 1 \\ 1 \end{bmatrix}, t \neq 0$$

Shortcut

(Espaces don't have to be 1-dim!!)

Ex 6 (p. 386)

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 5 & -10 \\ 1 & 0 & 2 & 0 \\ 1 & 0 & 0 & 3 \end{bmatrix}$$

Find evals (I'd give them)

$$\text{Solve } |\lambda I - A| = 0$$

$$(\lambda-1)^2(\lambda-2)(\lambda-3)=0$$

$\lambda_1=1$ has ^(algebraic) multiplicity, $\textcircled{2}$
 $\lambda_2=2$: : : : :
 $\lambda_3=3$: : : : :

The space for $\lambda_1=1$ could be 1-dim or 2-dim

When you solve

$$[(\lambda)I - A \mid \vec{0}]$$

$$\vec{x} = s \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 2 \\ 1 \end{bmatrix}$$

The space for $\lambda_1=1$ is 2-dim.

form a basis
(for the space for $\lambda_1=1$)

Ex
$$\begin{bmatrix} 1 & & \\ & 4 & \\ & & 4 \\ 0 & & 4 \end{bmatrix}$$

$\lambda=4$ has ^(algebraic) multiplicity 3
 Its space can have dim 1, 2 or 3.
 geometric mult'y.

Anton 353
 ? = algebraic mult.
 dimension =
 geometric mult.
 Can't use the "conjugate"
 what could dim of
 space be?