

FINAL - SOLUTIONS

MATH 254 - SUMMER 2002 - KUNIYUKI

GRADED OUT OF 100 POINTS $\times 2 = 200$ POINTS TOTAL

Assume that n represents a positive integer.

1) Find A^{10} if $A = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$. (3 points)

$$\begin{aligned} A^{10} &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{bmatrix}^{10} \\ &= \begin{bmatrix} (-1)^{10} & 0 & 0 \\ 0 & (2)^{10} & 0 \\ 0 & 0 & (-2)^{10} \end{bmatrix} \quad (\text{This works, because } A \text{ is a diagonal matrix.}) \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1024 & 0 \\ 0 & 0 & 1024 \end{bmatrix} \end{aligned}$$

2) Find the determinant below. (10 points)

$$\begin{vmatrix} 2 & 3 & 3 & 0 & 1 \\ 1 & -1 & -2 & 0 & 4 \\ 0 & 5 & 0 & 0 & 0 \\ 3 & 4 & 1 & 3 & -2 \\ 1 & 0 & 2 & 0 & 1 \end{vmatrix}$$

Let's expand along the third row, since it has many zeros. (The fourth column is also good.) Its only nonzero entry is the "5"; the corresponding sign from the sign matrix is "-" [or you could observe that $(-1)^{i+j} = (-1)^{3+2} = (-1)^5 = -1$]. To get the submatrix for the corresponding minor, we delete the row and the column containing the "5".

$$\begin{vmatrix} 2 & 3 & 3 & 0 & 1 \\ 1 & -1 & -2 & 0 & 4 \\ \mathbf{0} & \mathbf{5} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ 3 & 4 & 1 & 3 & -2 \\ 1 & 0 & 2 & 0 & 1 \end{vmatrix} = \underbrace{(-1)}_{\substack{\text{from} \\ \text{sign} \\ \text{matrix}}} (5) \begin{vmatrix} 2 & 3 & 0 & 1 \\ 1 & -2 & 0 & 4 \\ 3 & 1 & \mathbf{3} & -2 \\ 1 & 2 & 0 & 1 \end{vmatrix}$$

Let's expand along the third column. Its only nonzero entry is the "3"; the corresponding sign from the sign matrix is "+" [or you could observe that $(-1)^{i+j} = (-1)^{3+3} = (-1)^6 = +1$].

4) Let $\mathbf{v}_1 = (0, 3, 6, 0)$, $\mathbf{v}_2 = (0, 2, 4, 6)$, and $\mathbf{v}_3 = (1, -1, -2, 1)$.

Express $(4, -1, -2, -11)$ as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

The weights in this linear combination must be given as specific real numbers; don't just leave them as " c_i "s. (12 points)

$$\text{Solve } \left[\begin{array}{ccc|c} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 & \\ \hline & & & 4 \\ & & & -1 \\ & & & -2 \\ & & & -11 \end{array} \right] \text{ for } c_1, c_2, \text{ and } c_3, \text{ the weights for the linear combination.}$$

$$\left[\begin{array}{ccc|c} 0 & 0 & 1 & 4 \\ 3 & 2 & -1 & -1 \\ 6 & 4 & -2 & -2 \\ 0 & 6 & 1 & -11 \end{array} \right] \text{ Reorder the rows. Wrap around the first row to the bottom.}$$

$$\left[\begin{array}{ccc|c} 3 & 2 & -1 & -1 \\ 6 & 4 & -2 & -2 \\ 0 & 6 & 1 & -11 \\ 0 & 0 & 1 & 4 \end{array} \right] R_2 + (-2)R_1 \rightarrow R_2.$$

$$\left[\begin{array}{ccc|c} 3 & 2 & -1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 6 & 1 & -11 \\ 0 & 0 & 1 & 4 \end{array} \right] \text{ Reorder the rows. Make the zero row the new bottom row.}$$

$$\left[\begin{array}{ccc|c} 3 & 2 & -1 & -1 \\ 0 & 6 & 1 & -11 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ The matrix is in row-echelon shape. Good enough!}$$

Go further if you want to "officially" use Gaussian or Gauss-Jordan elimination.

$$\left\{ \begin{array}{l} 3c_1 + 2c_2 - c_3 = -1 \\ 6c_2 + c_3 = -11 \\ c_3 = 4 \\ 0 = 0 \text{ (Can ignore)} \end{array} \right.$$

Back-substitution:

$$\begin{array}{rcl} & & 3c_1 + 2c_2 - c_3 = -1 \\ & & 3c_1 + 2\left(-\frac{5}{2}\right) - (4) = -1 \\ & & 3c_1 - 5 - 4 = -1 \\ & & 3c_1 - 9 = -1 \\ & & 3c_1 = 8 \\ & & c_1 = \frac{8}{3} \\ c_3 = 4 & 6c_2 + c_3 = -11 & \\ & 6c_2 + 4 = -11 & \\ & 6c_2 = -15 & \\ & c_2 = -\frac{15}{6} & \\ & c_2 = -\frac{5}{2} & \end{array}$$

$$\text{So, } c_1 = \frac{8}{3}, c_2 = -\frac{5}{2}, \text{ and } c_3 = 4.$$

$$(4, -1, -2, -11) = \frac{8}{3}\mathbf{v}_1 - \frac{5}{2}\mathbf{v}_2 + 4\mathbf{v}_3$$

- 5) Find the angle between the vectors $(1, 3, 3)$ and $(2, 1, -4)$. Round off your answer to the nearest tenth of a degree. (For maximum accuracy, don't round off until the end.) (8 points)

Label the vectors \mathbf{v} and \mathbf{w} , respectively.

$$\begin{aligned} \cos \theta &= \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|} \\ &= \frac{(1, 3, 3) \cdot (2, 1, -4)}{\sqrt{(1)^2 + (3)^2 + (3)^2} \sqrt{(2)^2 + (1)^2 + (-4)^2}} \\ &= \frac{2 + 3 - 12}{\sqrt{19} \sqrt{21}} \\ &= \frac{-7}{\sqrt{19} \sqrt{21}} \\ &= -\frac{7}{\sqrt{399}} \quad (\approx -0.3504) \\ \theta &\approx 110.5^\circ \end{aligned}$$

- 6) $T: R^4 \rightarrow R^3$ is a linear transformation such that $T(\mathbf{v}) = A\mathbf{v}$, where A is the matrix below. (6 points total; 2 points each)

$$A = \begin{bmatrix} \mathbf{1} & 3 & -2 & 2 \\ 0 & 0 & \mathbf{4} & 3 \\ 0 & 0 & 0 & \mathbf{-5} \end{bmatrix}$$

A is already in row-echelon shape. Pivot positions are boldfaced.

- a) What is the dimension of the kernel of T ?

1. (Count the number of nonpivot columns in A .)

- b) Is T a one-to-one transformation? Circle one:

Yes

No

Not every column of A has a pivot position.

- c) Is T an onto transformation? Circle one:

Yes

No

Every row of A has a pivot position.

- 7) A is an $n \times n$ real matrix that has λ as a real eigenvalue. Prove that the (real) eigenspace for λ is a subspace of R^n , as we have done in class. Show all steps! (8 points)

Let W be the eigenspace for λ .

W must be nonempty, since an eigenvalue has eigenvectors by definition.

W is a subset of R^n .

Let \mathbf{x}_1 and \mathbf{x}_2 be any two members of W .

Then, $A\mathbf{x}_1 = \lambda\mathbf{x}_1$, and $A\mathbf{x}_2 = \lambda\mathbf{x}_2$ (even if \mathbf{x}_1 or \mathbf{x}_2 is $\mathbf{0}$).

Prove closure of W under vector addition:

Show $\mathbf{x}_1 + \mathbf{x}_2$ is in W - i.e., $A(\mathbf{x}_1 + \mathbf{x}_2) = \lambda(\mathbf{x}_1 + \mathbf{x}_2)$.

$$\begin{aligned} A(\mathbf{x}_1 + \mathbf{x}_2) &= A\mathbf{x}_1 + A\mathbf{x}_2 \\ &= \lambda\mathbf{x}_1 + \lambda\mathbf{x}_2 \\ &= \lambda(\mathbf{x}_1 + \mathbf{x}_2) \end{aligned}$$

So, $\mathbf{x}_1 + \mathbf{x}_2$ is in W .

Prove closure of W under scalar multiplication:

Let c be any real scalar.

Show $c \mathbf{x}_1$ is in W - i.e., $A(c \mathbf{x}_1) = \lambda(c \mathbf{x}_1)$.

$$\begin{aligned} A(c \mathbf{x}_1) &= c(A \mathbf{x}_1) \\ &= c(\lambda \mathbf{x}_1) \\ &= \lambda(c \mathbf{x}_1) \end{aligned}$$

So, $c \mathbf{x}_1$ is in W .

Note: You could prove both types of closure by showing that $c \mathbf{x}_1 + \mathbf{x}_2$ is in W .

QED

8) Orthogonally diagonalize the real symmetric matrix $A = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}$

by giving an orthogonal matrix P and a diagonal matrix D such that $D = P^{-1}AP$ (or, equivalently, $D = P^TAP$). Hint: The eigenvalues of A are 0 and 5; you don't have to show that. (16 points)

Find two orthogonal unit eigenvectors of A :

Find a unit eigenvector for $\lambda_1 = 0$:

Solve the system $[0I - A | \mathbf{0}]$, or $[-A | \mathbf{0}]$.

$$\left[\begin{array}{cc|c} -1 & 2 & 0 \\ 2 & -4 & 0 \end{array} \right]$$

The reduced row-echelon (RRE) form of this matrix is:

$$\left[\begin{array}{cc|c} 1 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Now, parametrize the solution set:

$$\begin{aligned} x_1 - 2x_2 = 0 &\rightarrow x_1 = 2x_2 \\ \text{Let } x_2 = t. & \end{aligned} \quad \begin{cases} x_1 = 2t \\ x_2 = t \end{cases}$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Let the eigenvector $\mathbf{p}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

We need our eigenvector to be a unit vector, so let's normalize:

$$\mathbf{u}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$$

Find a unit eigenvector for $\lambda_2 = 5$:

Solve the system $[5I - A | \mathbf{0}]$.

$$\left[\begin{array}{cc|c} 5-1 & 0-(-2) & 0 \\ 0-(-2) & 5-4 & 0 \end{array} \right]$$

$$\left[\begin{array}{cc|c} 4 & 2 & 0 \\ 2 & 1 & 0 \end{array} \right]$$

The reduced row-echelon (RRE) form of this matrix is:

$$\left[\begin{array}{cc|c} 1 & 1/2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Now, parametrize the solution set:

$$x_1 + \frac{1}{2}x_2 = 0 \rightarrow x_1 = -\frac{1}{2}x_2 \quad \begin{cases} x_1 = -\frac{1}{2}t \\ x_2 = t \end{cases}$$

Let $x_2 = t$.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$$

We can rescale $\begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$ by 2 and get the eigenvector $\mathbf{p}_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.

Note: You could have observed that we needed \mathbf{p}_2 to be orthogonal to \mathbf{p}_1 (i.e., $\mathbf{p}_1 \bullet \mathbf{p}_2 = 0$), and you could have figured out an appropriate \mathbf{p}_2 based on what we got for $\mathbf{p}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

We need our eigenvector to be a unit vector, so let's normalize:

$$\mathbf{u}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$$

Construct the diagonalizing orthogonal matrix, P :

$$P = [\mathbf{u}_1 \quad \mathbf{u}_2] \\ = \begin{bmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}$$

Give D :

Let $D = P^{-1}AP$ or, equivalently, $P^T AP$.

$$D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \\ = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix} \quad (\text{The eigenvalues are switched if the columns of } P \text{ are switched.})$$

- 9) Rewrite $\frac{1}{3-2i} \begin{bmatrix} 4+i & i \\ -2 & 0 \end{bmatrix}$ as an equivalent expression of the form $c \begin{bmatrix} z_1 & z_2 \\ z_3 & z_4 \end{bmatrix}$, where c is a real number, and the " z_i "s are complex numbers written in standard form. (8 points)

To rationalize the denominator in $\frac{1}{3-2i}$, we need to multiply the numerator and the denominator by the complex conjugate of the denominator.

$$\frac{1}{3-2i} \begin{bmatrix} 4+i & i \\ -2 & 0 \end{bmatrix} = \left(\frac{1}{3-2i} \right) \left(\frac{3+2i}{3+2i} \right) \begin{bmatrix} 4+i & i \\ -2 & 0 \end{bmatrix} \\ = \frac{3+2i}{(3)^2 + (-2)^2} \begin{bmatrix} 4+i & i \\ -2 & 0 \end{bmatrix} \quad (\text{Remember: } (a-bi)(a+bi) = a^2 - b^2i^2 = a^2 + b^2.) \\ = \frac{3+2i}{13} \begin{bmatrix} 4+i & i \\ -2 & 0 \end{bmatrix}$$

Now, multiply each entry of the matrix by $(3+2i)$.

$$= \frac{1}{13} \begin{bmatrix} (3+2i)(4+i) & (3+2i)(i) \\ (3+2i)(-2) & (3+2i)(0) \end{bmatrix} \\ = \frac{1}{13} \begin{bmatrix} 12 + 3i + 8i + \overbrace{2i^2}^{=(-2)} & 3i + \overbrace{2i^2}^{=(-2)} \\ -6 - 4i & 0 \end{bmatrix} \\ = \frac{1}{13} \begin{bmatrix} 10 + 11i & -2 + 3i \\ -6 - 4i & 0 \end{bmatrix}$$

- 10) Find $\|\mathbf{v}\|$, the Euclidean norm of \mathbf{v} , where $\mathbf{v} = (4 + i, 3)$ is a vector in C^2 . (4 points)

$$\begin{aligned} \|\mathbf{v}\| &= \sqrt{\mathbf{v} \bullet \mathbf{v}} \\ &= \sqrt{\sum_{i=1}^2 v_i \overline{v_i}} \\ &= \sqrt{(4+i)(4-i) + (3)(3)} & \text{or} & \quad \|\mathbf{v}\| = \sqrt{|v_1|^2 + |v_2|^2} \\ &= \sqrt{16 - \underbrace{i^2}_{=(-1)} + 9} & & \quad = \sqrt{|4+i|^2 + |3|^2} \\ &= \sqrt{16 + 1 + 9} & & \quad = \sqrt{17 + 9} \\ &= \sqrt{26} & & \quad = \sqrt{26} \end{aligned}$$

- 11) A is an $n \times n$ real matrix. For each statement below, circle “Yes” if it is equivalent to the statement “ A is invertible.” Otherwise, circle “No”. You do not have to justify your answers. (10 points total; 2 points each)

a) $\det(A) = 0$. Yes No

The correct equivalent statement is “ $\det(A) \neq 0$.”

b) A is diagonalizable. Yes No

For example, $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ is diagonal (and therefore diagonalizable) but not invertible.

c) A can be written as the product of elementary matrices. Yes No

See Theorem 2.14 on p.83.

d) $\text{rank}(A) = n$. Yes No

The reduced row-echelon (RRE) form of an $n \times n$ invertible matrix is I_n , the $n \times n$ identity matrix. I_n has n pivot positions, so its rank is n . Therefore, the rank of A had to be n , also. See p.221.

e) A is similar to I_n , the $n \times n$ identity matrix. Yes No

Only I_n is similar to I_n . If P is any invertible $n \times n$ matrix, then $P^{-1}I_nP = P^{-1}P = I_n$. There are many other invertible $n \times n$ matrices aside from I_n , however.

TRUE or FALSE (12 points; 3 points each)

Circle "True" or "False" (as appropriate) for each statement below.
You do not have to justify your answers.

Remember that you must circle "False" if the statement is "sometimes true, but sometimes false."

Assume that m and n represent positive integers and that all matrices are real.

- 1) If A and B are $n \times n$ matrices, then $(A + B)(A - B) = A^2 - B^2$.

True

False

$$\begin{aligned}(A + B)(A - B) &= AA - AB + BA - BB \\ &= A^2 - AB + BA - B^2\end{aligned}$$

It is not always true that $AB = BA$! For a counterexample, find two matrices A and B that do not commute (in a multiplicative sense).

- 2) If A is an $m \times n$ matrix, then $A^T A$ is symmetric.

True

False

A matrix is symmetric if and only if it equals its own transpose.
First of all, $A^T A$ is defined, because A^T is $n \times m$, and A is $m \times n$.
Prove that $(A^T A)^T = A^T A$: $(A^T A)^T = (A)^T (A^T)^T = A^T A$.
Remember that the transpose of a product equals the reverse product of transposes.

- 3) A set of 7 vectors in R^5 must span R^5 .

True

False

For example, this is not true if six of the vectors are scalar multiples of the seventh.

- 4) If A is an $m \times n$ matrix, then the set of all (compatible) vectors \mathbf{b} that make $A\mathbf{x} = \mathbf{b}$ consistent is a subspace of R^m .

True

False

In fact, this set is $\text{Col}(A)$, the column space of A , which is a subspace of R^m .
See Theorem 4.19 on p.220.