# FINAL - SOLUTIONS 

1) Find the inverse of the matrix

$$
A=\left[\begin{array}{lll}
0 & 4 & 0 \\
1 & 0 & 0 \\
0 & 0 & 2
\end{array}\right]
$$

(8 points)
Idea: $[A \mid I] \rightarrow\left[I \mid A^{-1}\right]$.
$[A \mid I]$
$\left[\begin{array}{lll|lll}0 & 4 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1\end{array}\right] \quad\left[\begin{array}{lll|lll}1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 4 & 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1\end{array}\right] \quad\left[\begin{array}{ccc|ccc}1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 / 4 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 / 2\end{array}\right]$
$R_{1} \leftrightarrow R_{2} \quad \frac{1}{4} R_{2} \rightarrow R_{2}$
$\frac{1}{2} R_{3} \rightarrow R_{3}$
So, $A^{-1}=\left[\begin{array}{ccc}0 & 1 & 0 \\ 1 / 4 & 0 & 0 \\ 0 & 0 & 1 / 2\end{array}\right]$
2) Find the determinant of the matrix

$$
A=\left|\begin{array}{cccc}
0 & 0 & 0 & \mathbf{2} \\
3 & 1 & 2 & 7 \\
6 & -2 & 3 & -1 \\
5 & 0 & 0 & 4
\end{array}\right|
$$

(10 points)
Let's expand along the first row, since it has the most zeros.
Its only nonzero entry is the " 2 "; the corresponding sign from the sign matrix is "-" [or you could observe that $\left.(-1)^{i+j}=(-1)^{1+4}=(-1)^{5}=-1\right]$. To get the submatrix for the corresponding minor, we delete the row and the column containing the "2".

$$
\left|\begin{array}{cccc}
\mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{2} \\
3 & 1 & 2 & 7 \\
6 & -2 & 3 & -1 \\
5 & 0 & 0 & 4
\end{array}\right|=\underset{\substack{\text { from sign } \\
\text { matrix }}}{(-1)}(2)\left|\begin{array}{ccc}
3 & 1 & 2 \\
6 & -2 & 3 \\
5 & 0 & 0
\end{array}\right|=-2\left|\begin{array}{ccc}
3 & 1 & 2 \\
6 & -2 & 3 \\
\mathbf{5} & 0 & 0
\end{array}\right|
$$

Let's expand along the third row, since it has the most zeros.
Its only nonzero entry is the " 5 "; the corresponding sign from the sign matrix is " + " [or you could observe that $\left.(-1)^{i+j}=(-1)^{3+1}=(-1)^{4}=1\right]$. To get the submatrix for the corresponding minor, we delete the row and the column containing the " 5 ".

$$
\begin{aligned}
-2\left|\begin{array}{ccc}
3 & 1 & 2 \\
6 & -2 & 3 \\
\mathbf{5} & \mathbf{0} & \mathbf{0}
\end{array}\right| & =-2\left(5\left|\begin{array}{cc}
1 & 2 \\
-2 & 3
\end{array}\right|\right) \\
& =-2(5(3-(-4))) \\
& =-2(5(7)) \\
& =-70
\end{aligned}
$$

3) Let $\mathbf{v}_{1}=(1,2)$ and $\mathbf{v}_{2}=(3,5)$. Express $(-7,-9)$ as a linear combination of $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$. There should be no unknowns in your final expression. (10 points)

Solve $\left[\begin{array}{ll|l}\mathbf{v}_{1} & \mathbf{v}_{2} & -7 \\ \hline\end{array}\right]$ for $c_{1}$ and $c_{2}$, the weights for the linear combination.
$\left[\begin{array}{ll|l}1 & 3 & -7 \\ 2 & 5 & -9\end{array}\right] \quad\left[\begin{array}{cc|c}1 & 3 & -7 \\ 0 & -1 & 5\end{array}\right]$
$\left[\begin{array}{cc|c}1 & 0 & 8 \\ 0 & -1 & 5\end{array}\right]$
$\left[\begin{array}{cc|c}1 & 0 & 8 \\ 0 & 1 & -5\end{array}\right]$
$R_{2}-2 R_{1} \rightarrow R_{2} \quad R_{1}+3 R_{2} \rightarrow R_{1} \quad-R_{2} \rightarrow R_{2}$

So, $c_{1}=8$ and $c_{2}=-5$.
$\left[\begin{array}{l}-7 \\ -9\end{array}\right]=8 \mathbf{v}_{1}-5 \mathbf{v}_{2}$
4) The vectors $\mathbf{x}, \mathbf{y}$, and $\mathbf{z}$ are three vectors in $R^{n}$ for some fixed $n$.

Prove that if $\mathbf{x}$ is orthogonal to both $\mathbf{y}$ and $\mathbf{z}$, then $\mathbf{x}$ is orthogonal to any linear combination of $\mathbf{y}$ and $\mathbf{z}$. (10 points)

Assume that $\mathbf{x}$ is orthogonal to $\mathbf{y}$ and $\mathbf{z}$. Then, $\mathbf{x} \cdot \mathbf{y}=0$, and $\mathbf{x} \cdot \mathbf{z}=0$.
Let $c \mathbf{y}+d \mathbf{z}$ be any linear combination of $\mathbf{y}$ and $\mathbf{z}$, where $c$ and $d$ are real numbers.
We need to show that $\mathbf{x} \cdot(c \mathbf{y}+d \mathbf{z})=0$.

$$
\begin{aligned}
\mathbf{x} \bullet(c \mathbf{y}+d \mathbf{z}) & =(\mathbf{x} \bullet c \mathbf{y})+(\mathbf{x} \bullet d \mathbf{z}) \\
& =c(\mathbf{x} \bullet \mathbf{y})+d(\mathbf{x} \bullet \mathbf{z}) \\
& =c(0)+d(0) \\
& =0
\end{aligned}
$$

5) The linear transformation $T: R^{5} \rightarrow R^{4}$ is defined by $T(\mathbf{x})=A \mathbf{x}$, where

$$
A=\left[\begin{array}{ccccc}
1 & 0 & 4 & 3 & 0 \\
0 & 1 & -2 & 5 & 0 \\
0 & 0 & 0 & 0 & 3 \\
2 & 0 & 8 & 6 & 0
\end{array}\right]
$$

Find a basis for the Range of $T$. (10 points)
Note that if we perform $R_{4}-2 R_{1} \rightarrow R_{4}$, we obtain the row-echelon "shape"

$$
B=\left[\begin{array}{ccccc}
\mathbf{1} & 0 & 4 & 3 & 0 \\
0 & \mathbf{1} & -2 & 5 & 0 \\
0 & 0 & 0 & 0 & \mathbf{3} \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

You could also divide the third row by 3 to get reduced row-echelon (RRE) form.
Range $(T)=\operatorname{Col}(A)$, the column space of $A$. To get a basis for $\operatorname{Col}(A)$, take the columns of $A$ that correspond to the pivot columns of the row-echelon "shape" $B$. In other words, we take columns 1, 2, and 5 of $A$.

Answer: $\left\{\left[\begin{array}{l}1 \\ 0 \\ 0 \\ 2\end{array}\right],\left[\begin{array}{l}0 \\ 1 \\ 0 \\ 0\end{array}\right],\left[\begin{array}{l}0 \\ 0 \\ 3 \\ 0\end{array}\right]\right\}$. (There are other possible answers.)
Note: You could also find a basis for $\operatorname{Row}\left(A^{T}\right)$.
6) Orthogonally diagonalize the symmetric matrix

$$
A=\left[\begin{array}{ll}
1 & 4 \\
4 & 1
\end{array}\right]
$$

by giving an orthogonal matrix $P$ and a diagonal matrix $D$ such that $D=P^{-1} A P$ (or, equivalently, $D=P^{T} A P$ ).

Hint: The eigenvalues of this matrix $(A)$ are -3 and 5 .
(25 points)

Find two orthogonal eigenvectors of $A$ :
Find an eigenvector for $\lambda_{1}=-3$ :
Solve the system $[-3 I-A \mid \mathbf{0}]$.

$$
\begin{gathered}
{\left[\begin{array}{cc|c}
-3-1 & 0-4 & 0 \\
0-4 & -3-1 & 0
\end{array}\right]} \\
{\left[\begin{array}{ll|l}
-4 & -4 & 0 \\
-4 & -4 & 0
\end{array}\right]}
\end{gathered}
$$

The reduced row-echelon (RRE) form of this matrix is:

$$
\left[\begin{array}{ll|l}
1 & 1 & 0 \\
0 & 0 & 0
\end{array}\right]
$$

Now, parametrize the solution set:

$$
\begin{aligned}
& x_{1}+x_{2}=0 \rightarrow x_{1}=-x_{2} \\
& \text { Let } x_{2}=t . \\
& \qquad\left\{\begin{array}{l}
x_{1}=-t \\
x_{2}=t
\end{array}\right. \\
& \mathbf{x}=\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]=t\left[\begin{array}{c}
-1 \\
1
\end{array}\right]
\end{aligned}
$$

Let the eigenvector $\mathbf{p}_{1}=\left[\begin{array}{c}-1 \\ 1\end{array}\right]$.
We need our eigenvector to be a unit vector, so let's normalize:

$$
\mathbf{u}_{1}=\frac{1}{\sqrt{2}}\left[\begin{array}{c}
-1 \\
1
\end{array}\right]=\left[\begin{array}{c}
-1 / \sqrt{2} \\
1 / \sqrt{2}
\end{array}\right]
$$

Find an eigenvector for $\lambda_{2}=5$ :
Solve the system $[5 I-A \mid \mathbf{0}]$.

$$
\left[\begin{array}{cc|c}
5-1 & 0-4 & 0 \\
0-4 & 5-1 & 0
\end{array}\right]
$$

$$
\left[\begin{array}{cc|c}
4 & -4 & 0 \\
-4 & 4 & 0
\end{array}\right]
$$

The reduced row-echelon (RRE) form of this matrix is:

$$
\left[\begin{array}{cc|c}
1 & -1 & 0 \\
0 & 0 & 0
\end{array}\right]
$$

Now, parametrize the solution set:

$$
\begin{aligned}
& x_{1}-x_{2}=0 \rightarrow x_{1}=x_{2} \\
& \text { Let } x_{2}=t . \\
& \qquad\left\{\begin{array}{l}
x_{1}=t \\
x_{2}=t
\end{array}\right. \\
& \qquad \mathbf{x}=\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]=t\left[\begin{array}{l}
1 \\
1
\end{array}\right]
\end{aligned}
$$

Let the eigenvector $\mathbf{p}_{2}=\left[\begin{array}{l}1 \\ 1\end{array}\right]$.
We need our eigenvector to be a unit vector, so let's normalize:

$$
\mathbf{u}_{2}=\frac{1}{\sqrt{2}}\left[\begin{array}{l}
1 \\
1
\end{array}\right]=\left[\begin{array}{l}
1 / \sqrt{2} \\
1 / \sqrt{2}
\end{array}\right]
$$

Construct the diagonalizing orthogonal matrix, $P$ :

$$
\begin{aligned}
P & =\left[\begin{array}{ll}
\mathbf{u}_{1} & \mathbf{u}_{2}
\end{array}\right] \\
& =\left[\begin{array}{cc}
-1 / \sqrt{2} & 1 / \sqrt{2} \\
1 / \sqrt{2} & 1 / \sqrt{2}
\end{array}\right]
\end{aligned}
$$

Give $D$ :
Let $D=P^{-1} A P$ or, equivalently, $P^{T} A P$.

$$
\begin{aligned}
D & =\left[\begin{array}{cc}
\lambda_{1} & 0 \\
0 & \lambda_{2}
\end{array}\right] \\
& =\left[\begin{array}{cc}
-3 & 0 \\
0 & 5
\end{array}\right] \text { (The eigenvalues are switched if } P^{\prime} \text { s columns are switched.) }
\end{aligned}
$$

7) $A$ and $P$ are $n \times n$ matrices. If $\operatorname{det}(A)=4$, and $\operatorname{det}(P)=7$, what is $\operatorname{det}\left(P^{-1} A P\right)$ ? (6 points)

$$
\begin{aligned}
\left|P^{-1} A P\right| & =\left|P^{-1}\right| A \||P| \\
& =\frac{1}{|P|}|A \| P| \\
& =\frac{1}{7}(4)(7) \\
& =4
\end{aligned}
$$

Note that $\left|P^{-1} A P\right|=|A|$, regardless of what $|P|$ is, as long as it is nonzero and hence $P$ is invertible. In other words, similar matrices have not just the same eigenvalues, but also the same determinant (in fact, the common determinant equals the product of eigenvalues, accounting for multiplicities).

## TRUE OR FALSE

For each statement, circle "True" or "False" as appropriate.
You do not have to justify any of your responses.
(21 points; 3 points each)
(I noticed a bit too late that the True/False answers alternated.)
a) A homogeneous system of linear equations must be consistent.

$$
\text { True } \quad \text { False }
$$

$A \mathbf{x}=\mathbf{0}$ always has $\mathbf{x}=\mathbf{0}$ as a solution.
b) If $A, B$, and $C$ are $n \times n$ matrices, and if $A B=A C$, then it must be true that $B=C$.

True
False
The statement is true if $A$ is invertible, but it is not generally true.
For example, what if $A$ is the zero matrix?
c) All elementary matrices are invertible.

## True False

The inverse of an elementary matrix corresponds to the ERO that undoes the ERO represented by the elementary matrix.
d) The set of rational numbers is a subspace of $\mathbf{R}$, the vector space of real numbers.

$$
\text { True } \quad \text { False }
$$

The set of rational numbers is not closed under scalar multiplication. For example, 1 is a rational number, and $\pi$ is a real scalar, but $\pi(1)=\pi$, which falls outside the set of rational numbers.
e) A set of five vectors in $R^{3}$ must be linearly dependent.

$$
\text { True } \quad \text { False }
$$

Anytime the number of vectors exceeds the dimension of the space, the set of vectors must be linearly dependent.
f) A set of five vectors in $R^{3}$ must span $R^{3}$.

True
False

For example, the five vectors could all be $\mathbf{0}$.
$\mathrm{g})$ If the linear transformation $T: R^{3} \rightarrow R^{4}$ is defined by $T(\mathbf{x})=A \mathbf{x}$, where
$A=\left[\begin{array}{ccc}\mathbf{2} & 3 & 2 \\ 0 & \mathbf{1} & -5 \\ 0 & 0 & \mathbf{4} \\ 0 & 0 & 0\end{array}\right]$, then $T$ is a one-to-one transformation.

## True False

Notice that $A$ is already in row-echelon "shape" and that each column has a pivot position (i.e., the columns of $A$ form a linearly independent set). $T$ is then a one-to-one transformation. This is equivalent to saying that $A \mathbf{x}=\mathbf{b}$ can never have more than one solution.

